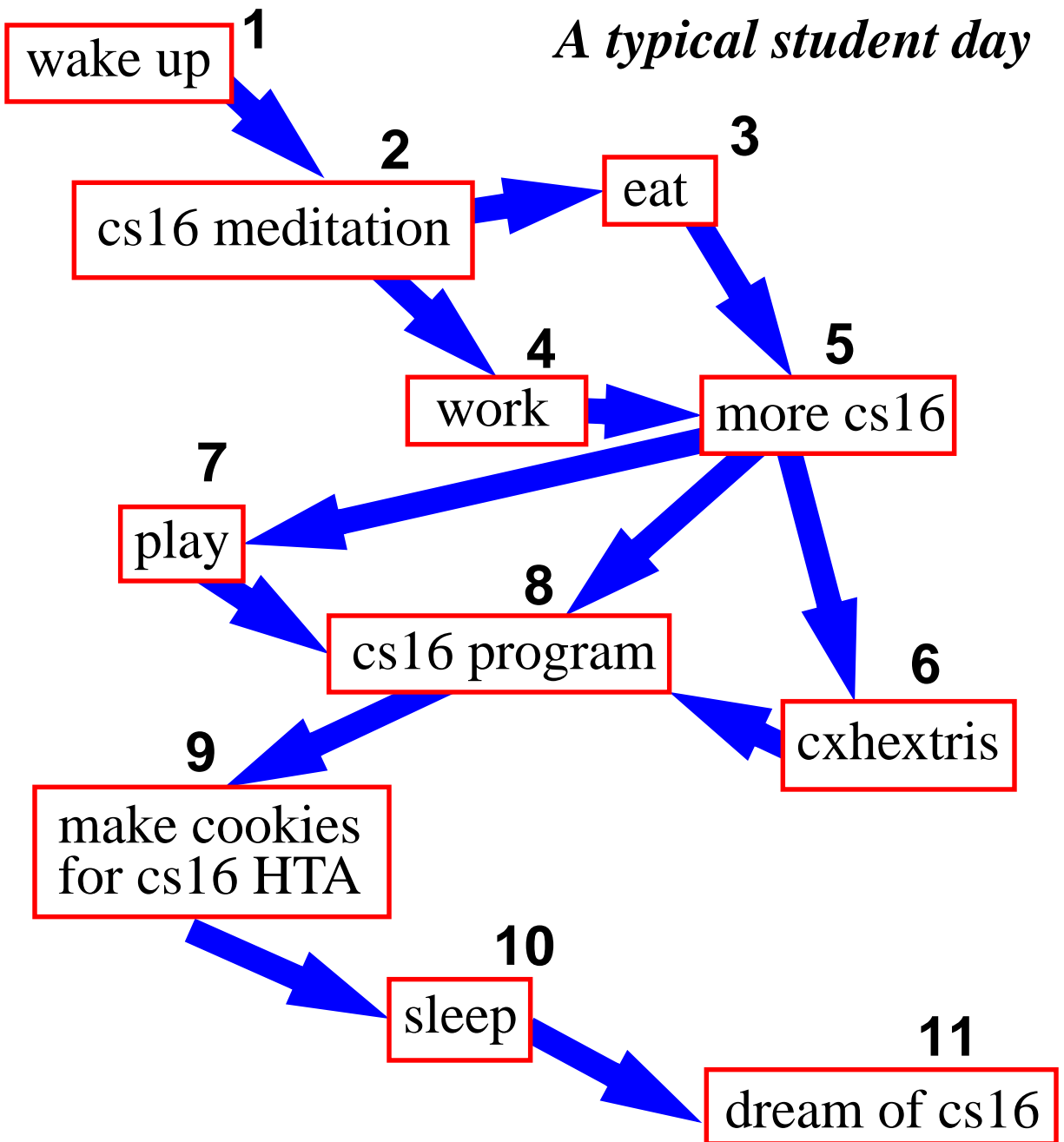


DIGRAPHS

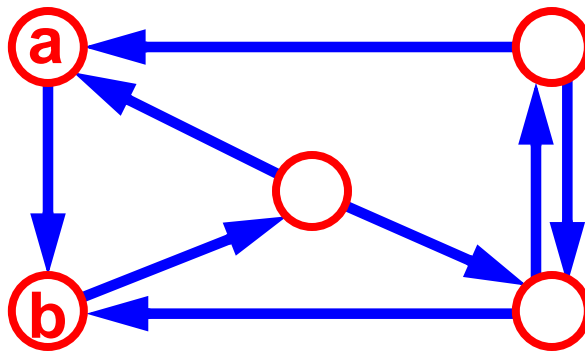


What's a Digraph?

- a) A small burrowing animal with long sharp teeth and a unquenchable lust for the blood of computer science majors
- b) A distressed graph
- c) A directed graph

Each edge goes in one direction

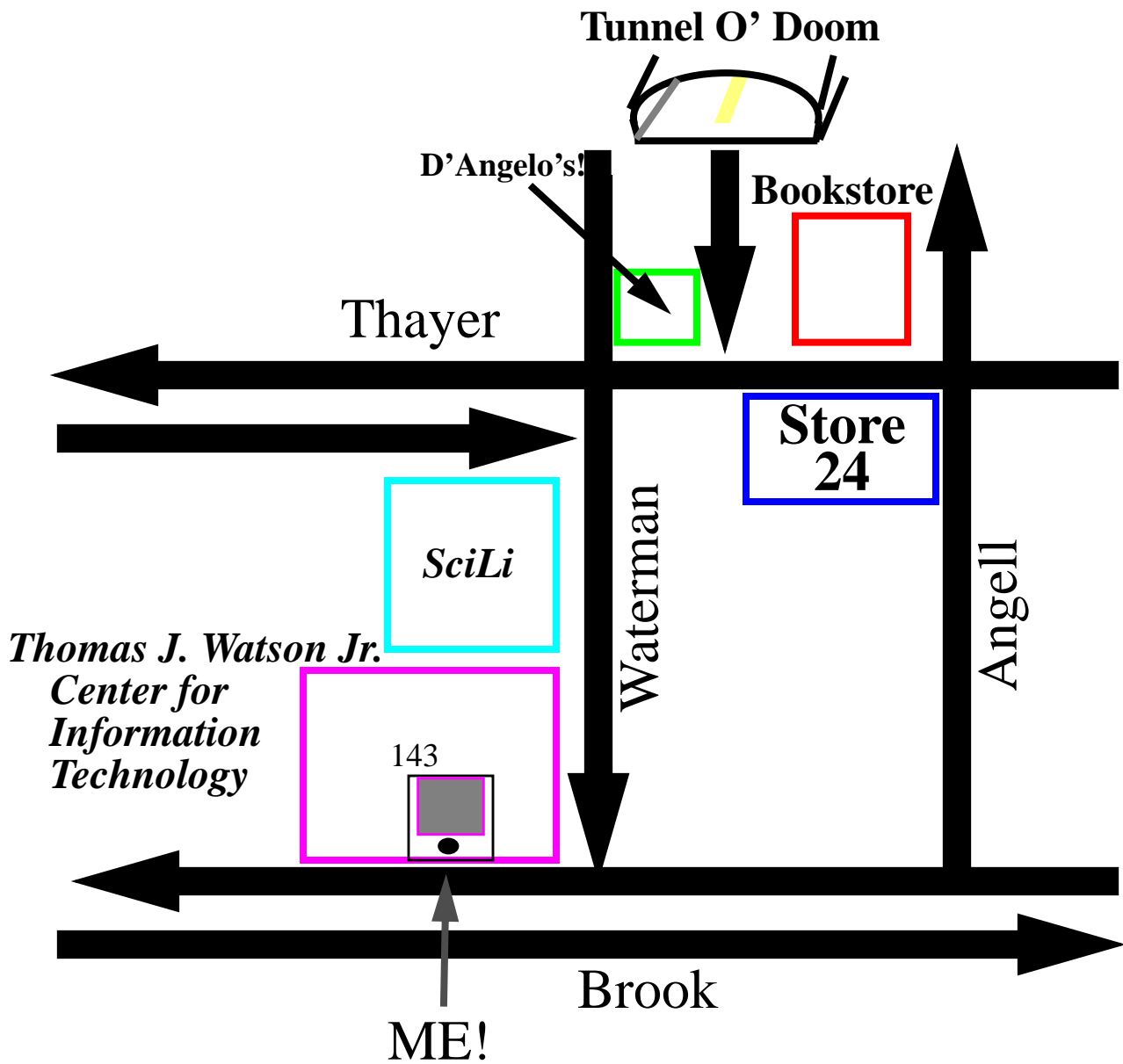
Edge (a,b) goes from a to b, but not b to a



You're saying, "Yo, how about an example of how we might be enlightened by the use of digraphs!!" – Well, if you insist. . .

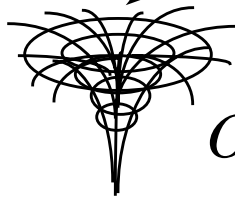
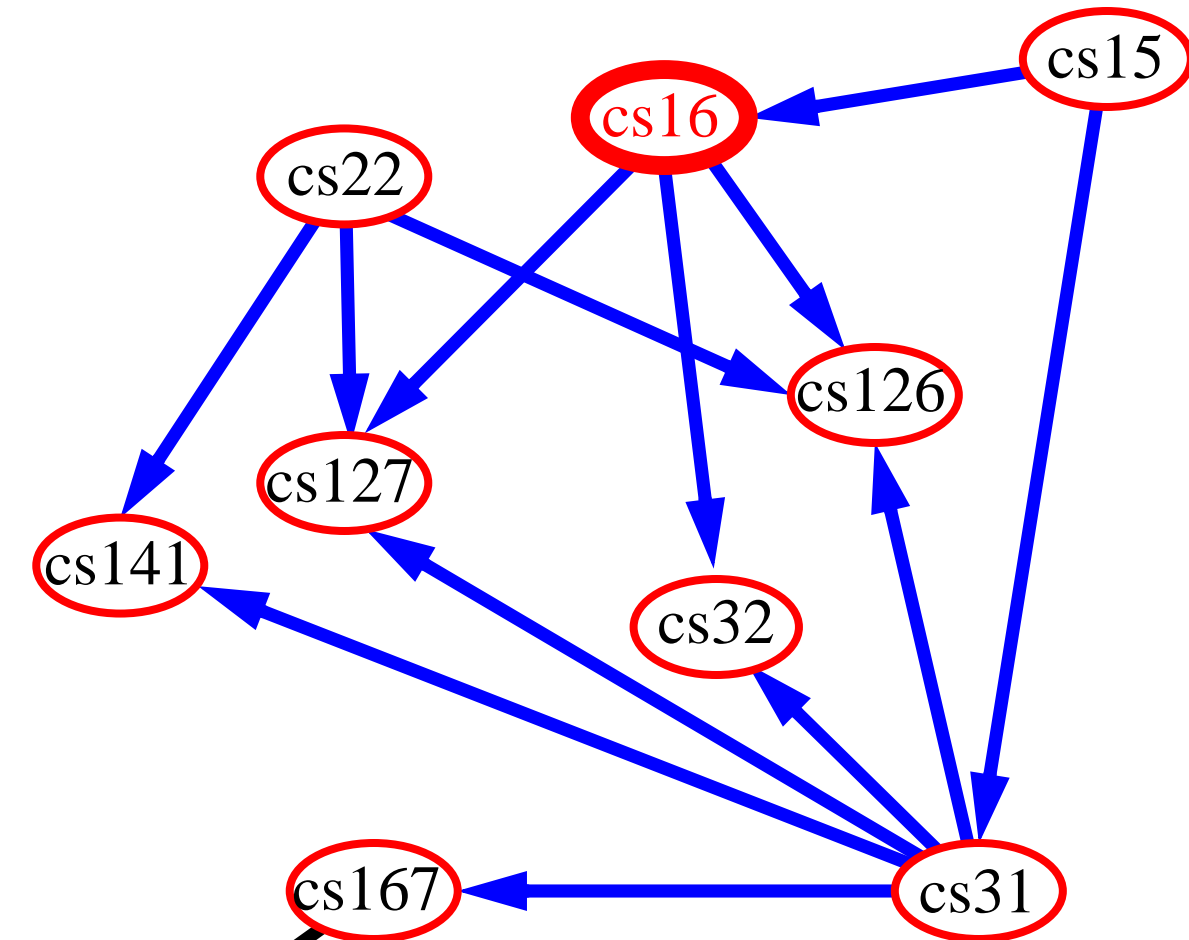
Applications

Maps: digraphs handle one-way streets
(especially helpful in Providence)



Another Application

Scheduling: edge **(a,b)** means task **a** must be completed before **b** can be started



*Old programmers never die -
they just fall into black holes*

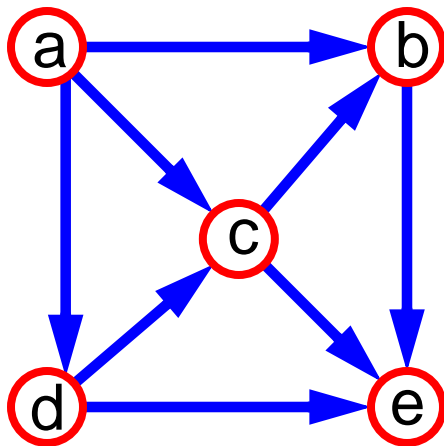
DAG's

dag: (noun) dâ-g

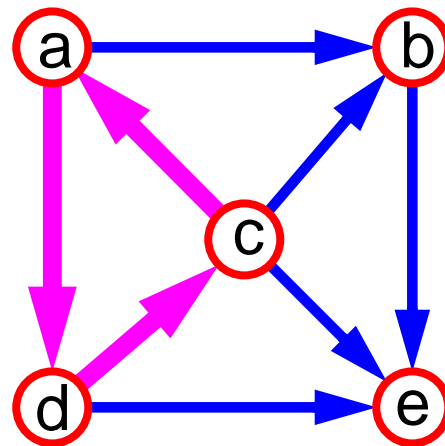
1. **Di-Acyl-Glycerol** – My favorite snack!
2. “~~man~~’s best friend”
person’s
3. **directed acyclic graph**

Say What?!

directed graph with **no directed cycles**



DAG

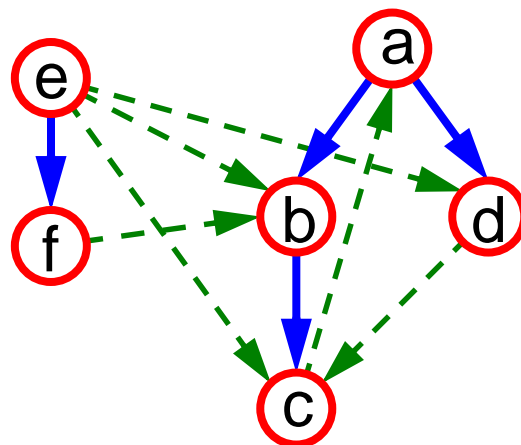
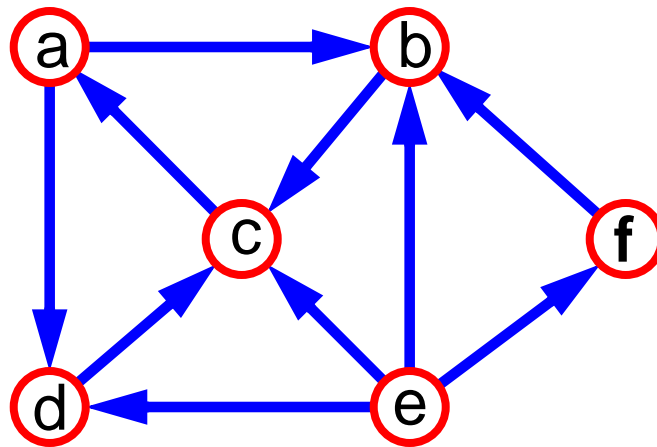


not a DAG

Depth-First Search

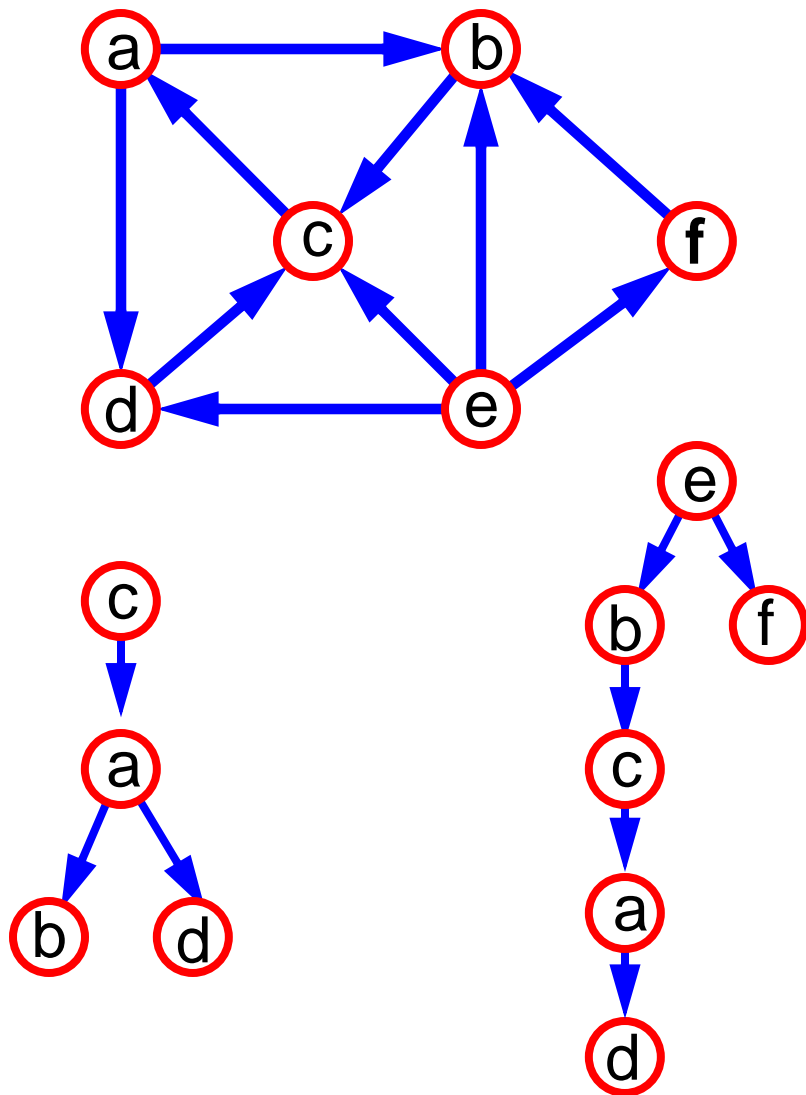
Same algorithm as for undirected **graphs**

On a connected digraph, may yield unconnected DFS trees (i.e., a DFS forest)



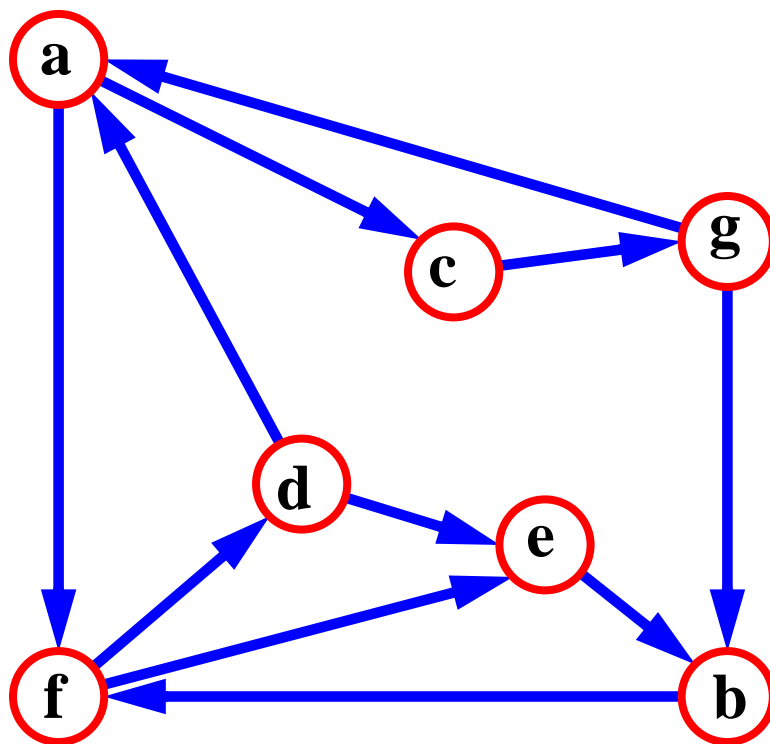
Reachability

DFS **tree** rooted at **v**: vertices reachable from **v** via directed paths

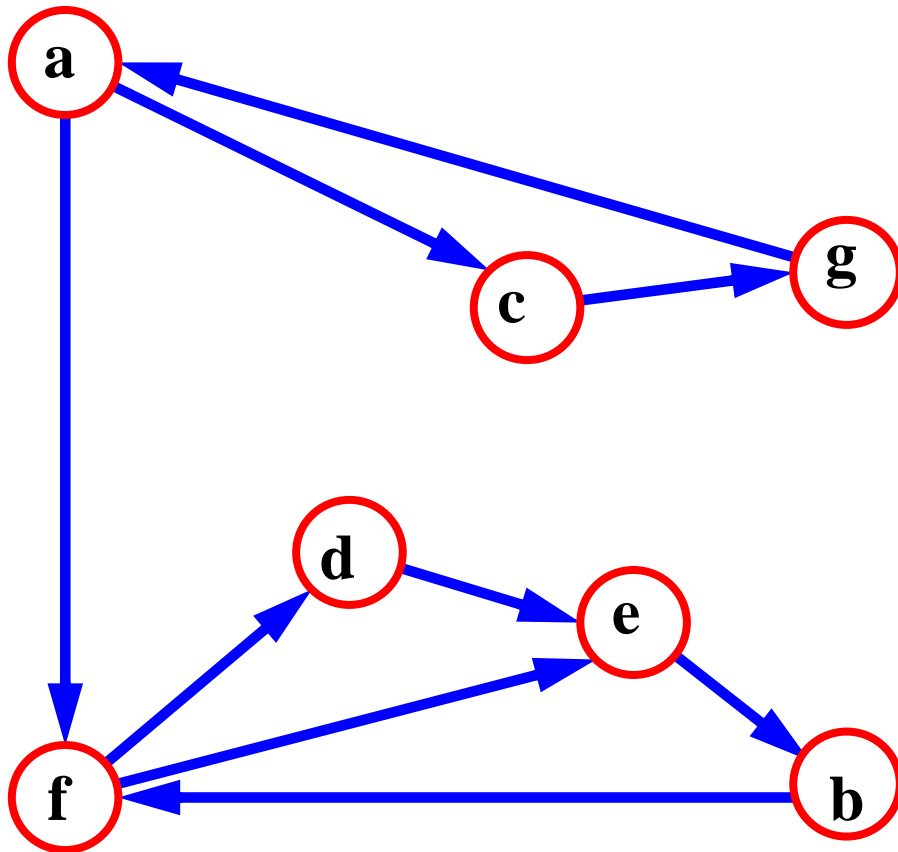


Strongly Connected Digraphs

Each vertex can reach all other vertices



Strongly Connected Components



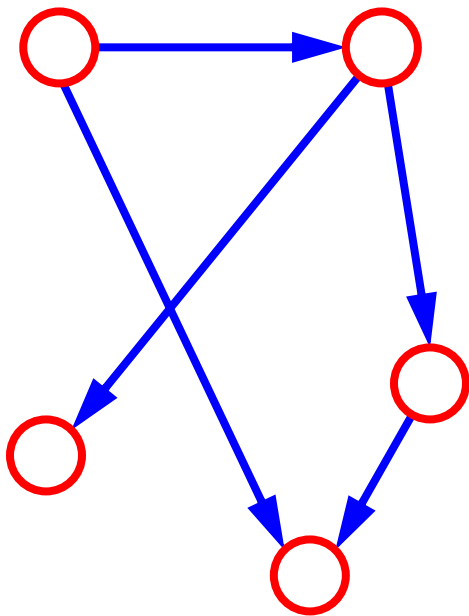
$\{ a , c , g \}$

$\{ f , d , e , b \}$

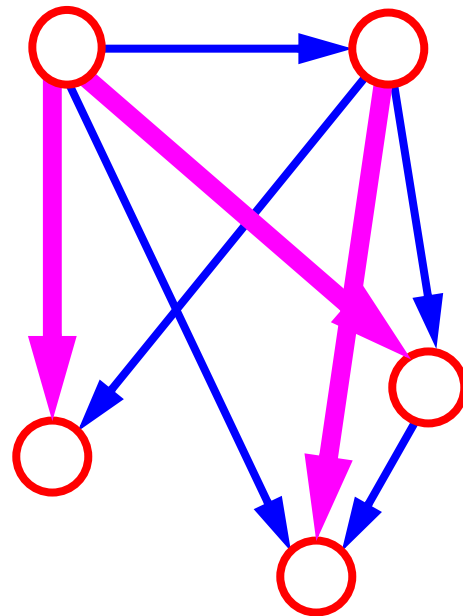
Transitive Closure

Digraph G^* is obtained from G using the rule:

If there is a directed path in G from a to b , then **add the edge (a,b)** to G^*



G



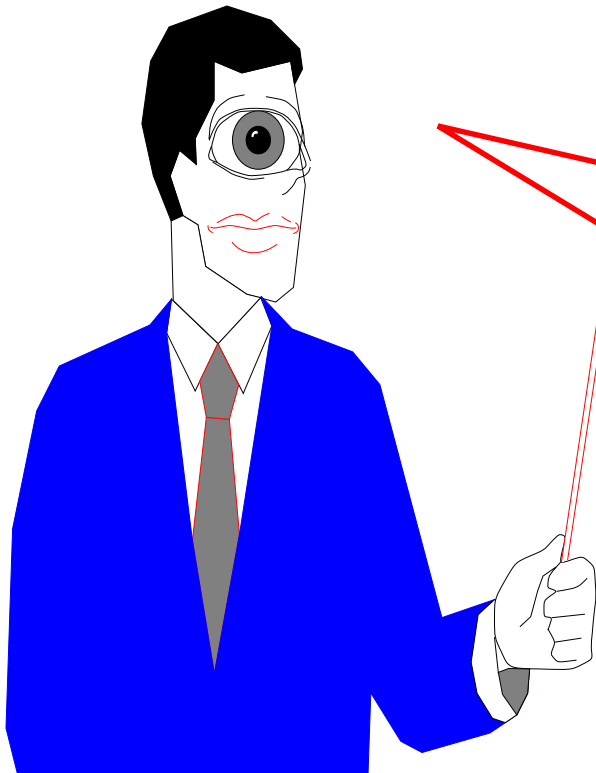
G^*

Computing the Transitive Closure

We can perform DFS starting at each vertex

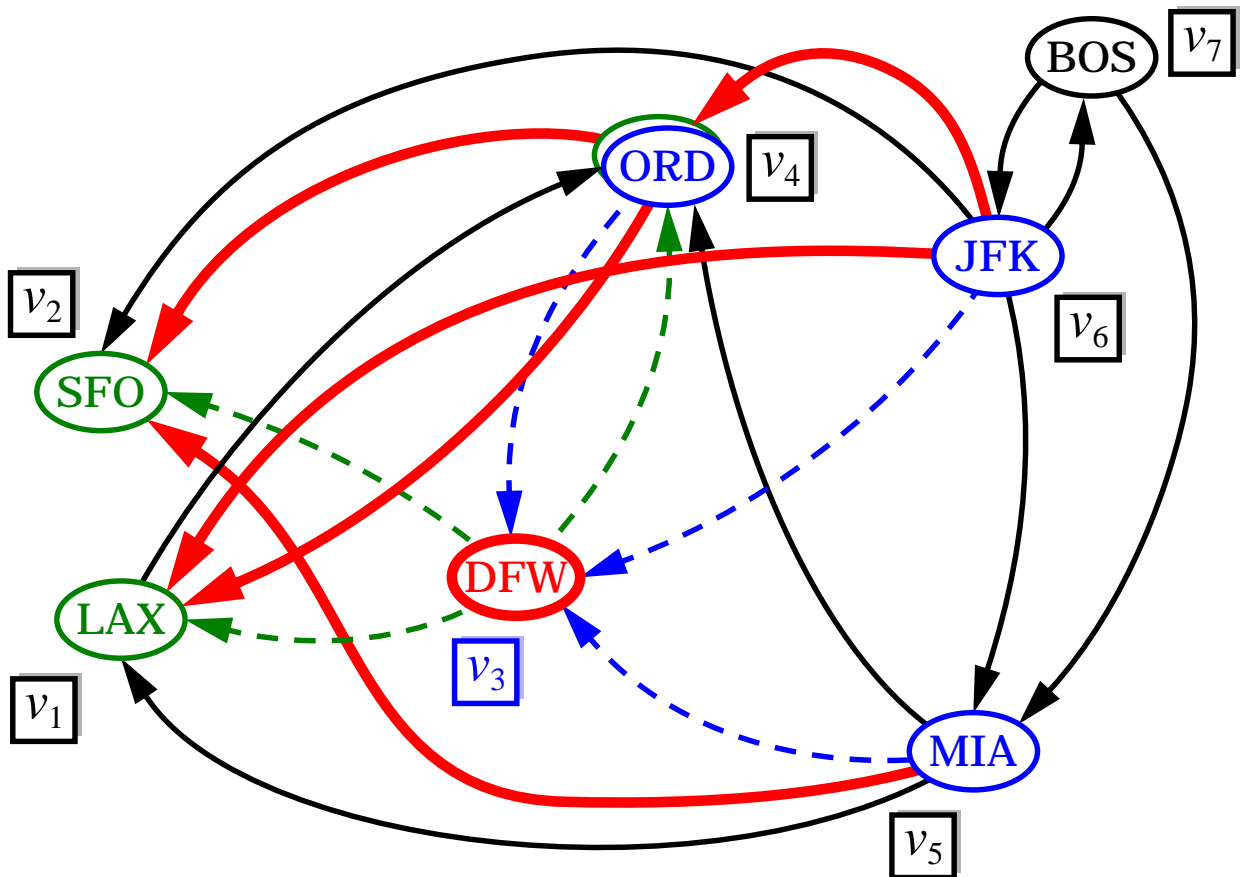
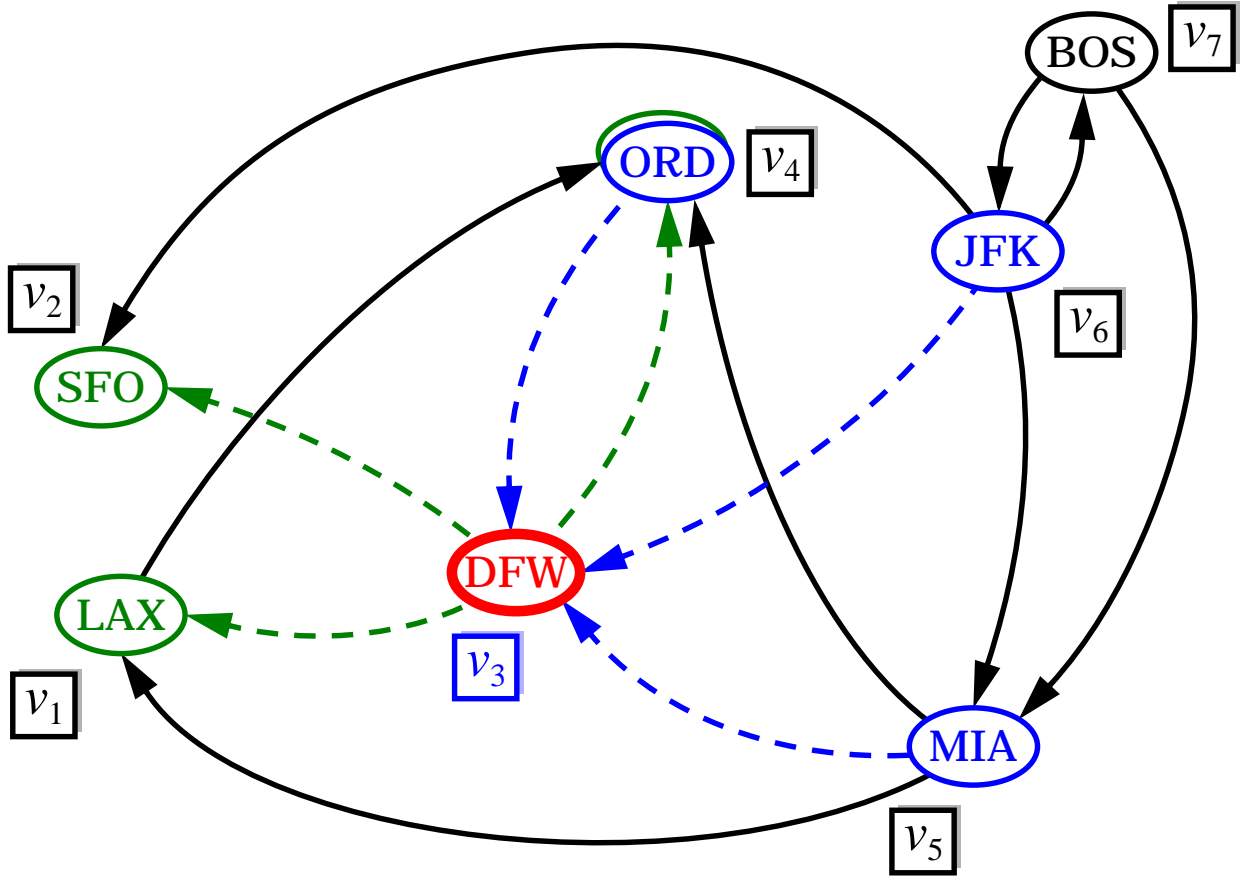
Time: $O(n(n+m))$

Alternatively ... Floyd-Warshall Algorithm:



If there's a way to get from **a** to **b**, and from **b** to **c**, then there's a way to get from **a** to **c**

Example



Floyd-Warshall Algorithm

- this algorithm assumes that methods `areAdjacent` and `insertDirectedEdge` take $O(1)$ time (e.g., adjacency matrix structure)

Algorithm `FloydWarshall(G)`

let $v_1 \dots v_n$ be an arbitrary ordering of the vertices

$G_0 = G$

for $k = 1$ **to** n **do**

// consider all possible routing vertices v_k

$G_k = G_{k-1}$

for each $(i, j = 1, \dots, n)$ ($i \neq j$) ($i, j \neq k$) **do**

// for each pair of vertices v_i and v_j

if $G_{k-1}.\text{areAdjacent}(v_i, v_k)$ **and**

$G_{k-1}.\text{areAdjacent}(v_k, v_j)$ **then**

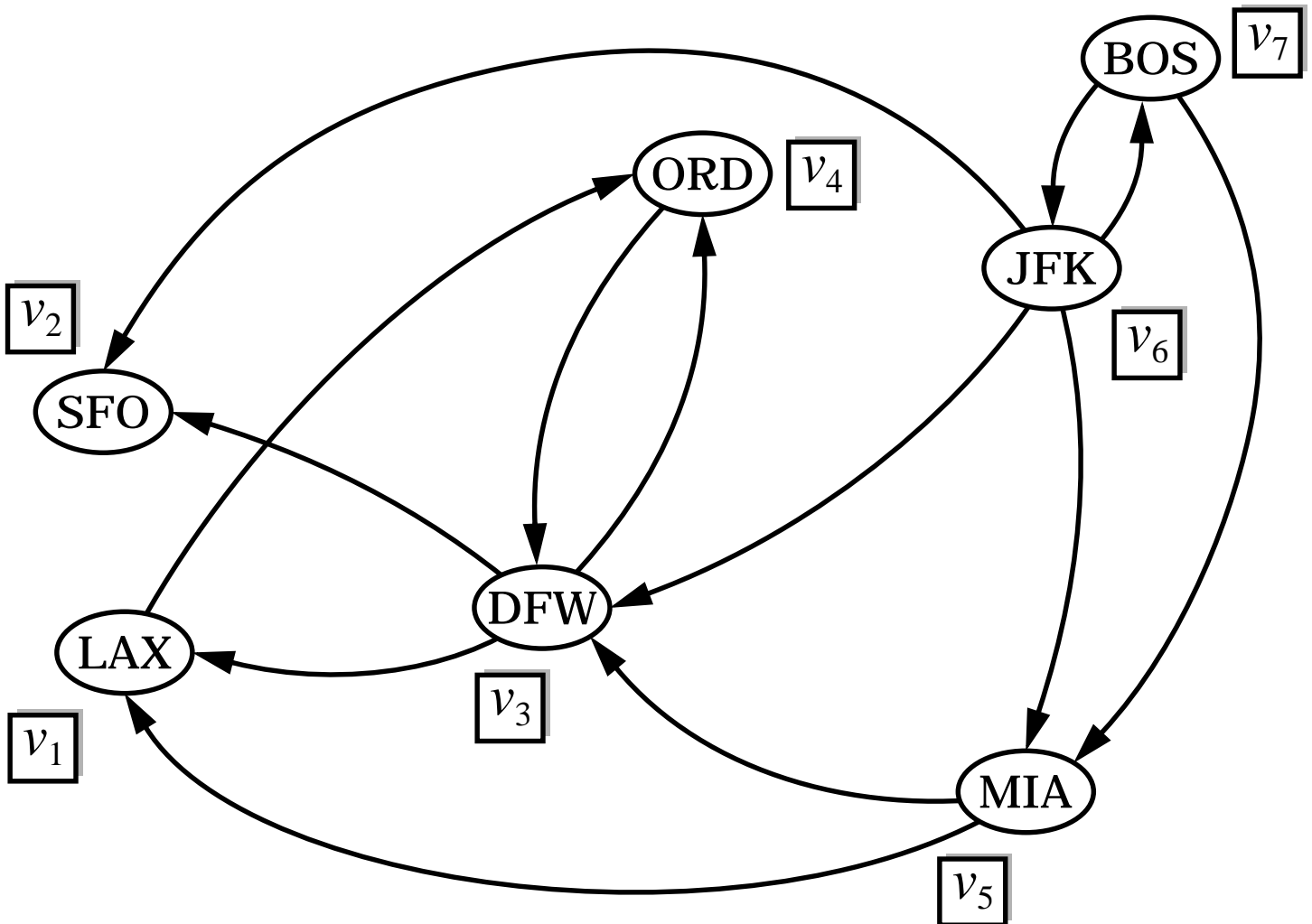
$G_k.\text{insertDirectedEdge}(v_i, v_j, \text{null})$

return G_0

- digraph G_k is the subdigraph of the transitive closure of G induced by paths with intermediate vertices in the set $\{v_1, \dots, v_k\}$
- running time: $O(n^3)$

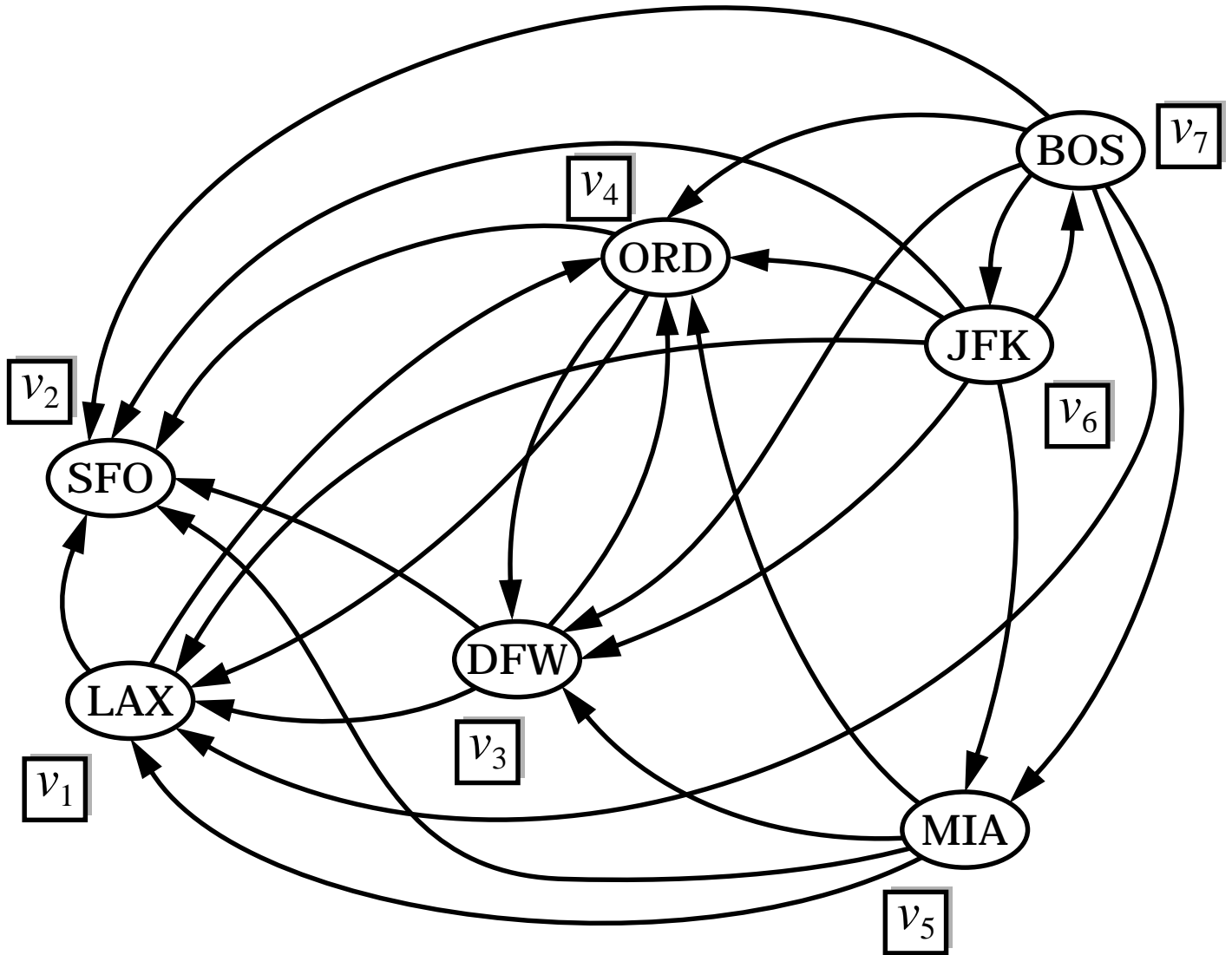
Example

- digraph G



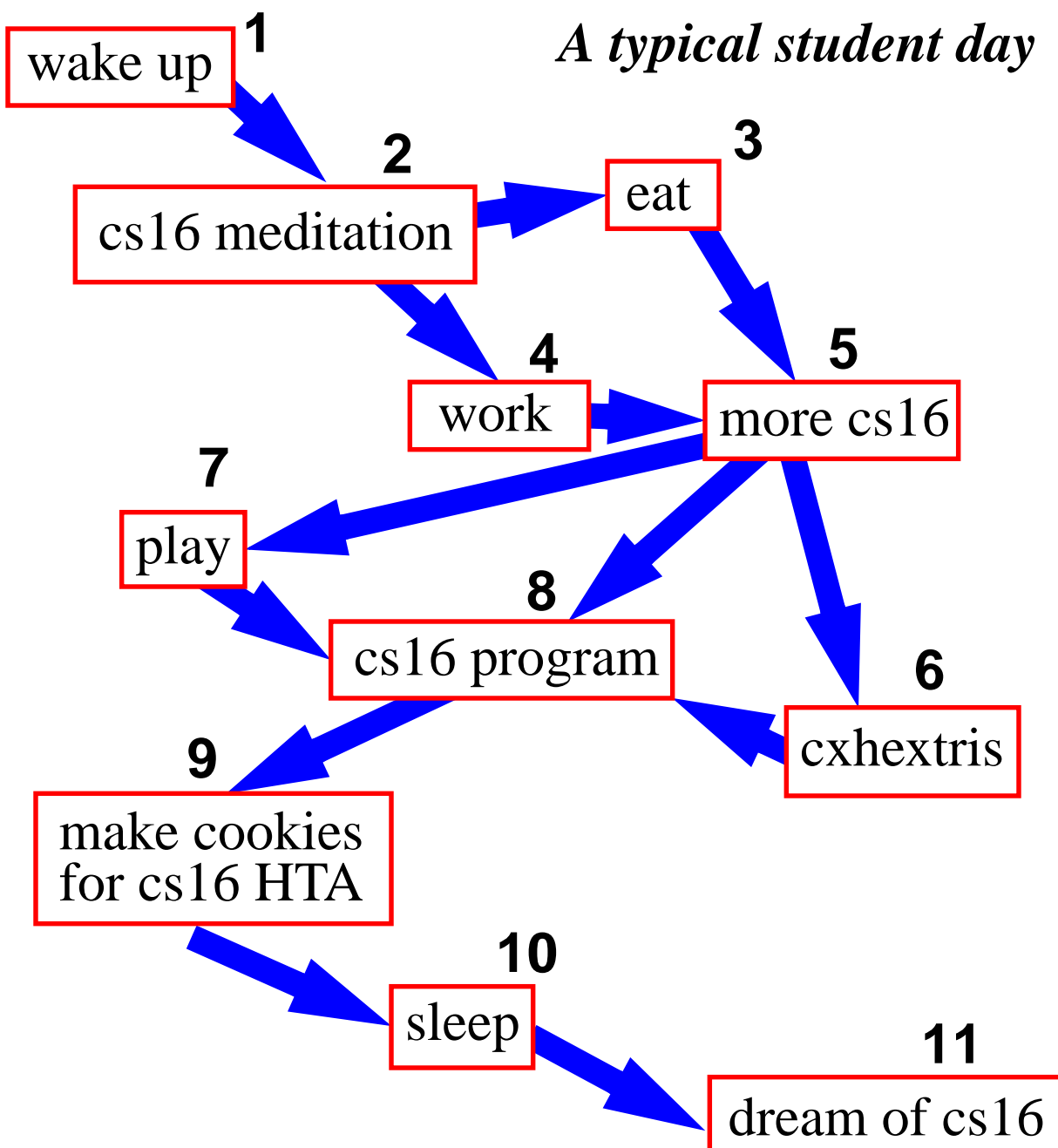
Example

- digraph G^*



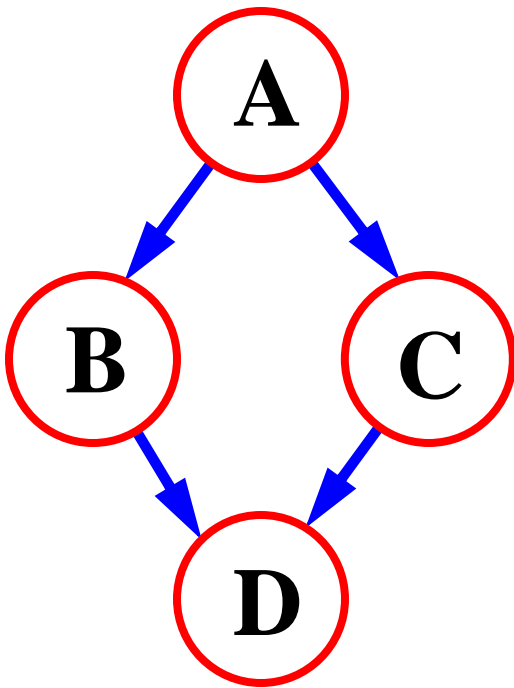
Topological Sorting

For each edge (u,v) , vertex u is visited before vertex v



Topological Sorting

Topological sorting may **not** be
unique



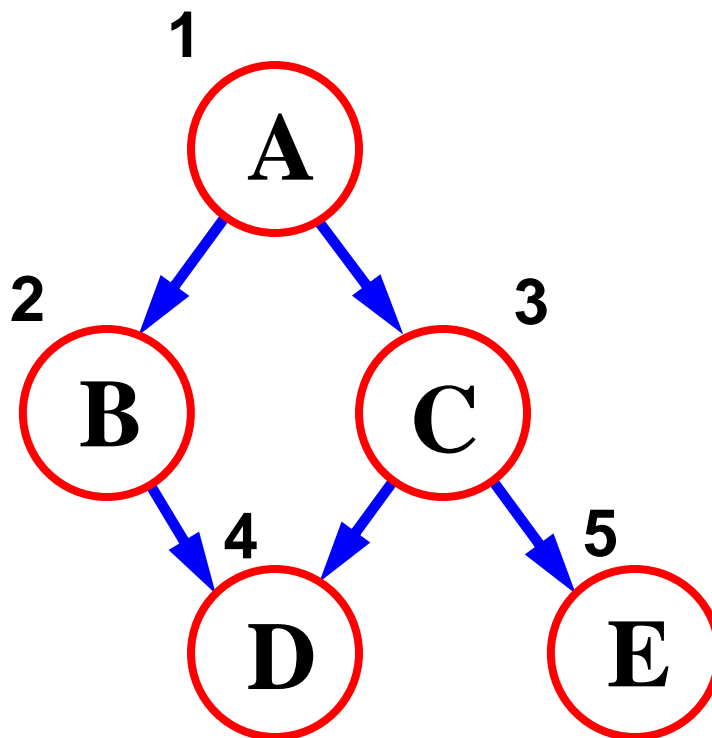
A B C D
or
A C B D

– *You make the call!*

Topological Sorting

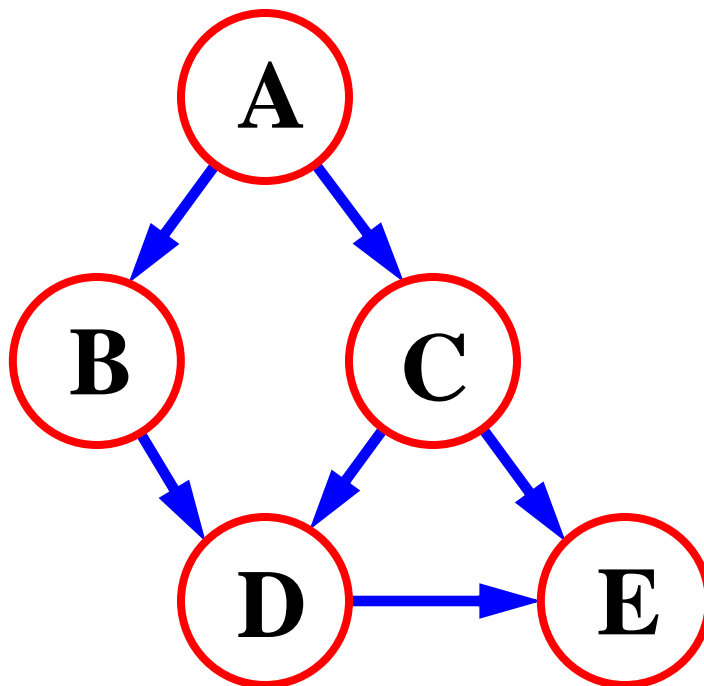
Labels are increasing along a directed path

A digraph has a topological sorting *if and only if* it is acyclic (i.e., a dag)



Algorithm for Topological Sorting

```
method TopologicalSort  
  if there are more vertices  
    let  $v$  be a source;  
    // a vertex w/o incoming edges  
    label and remove  $v$ ;  
    TopologicalSort;
```



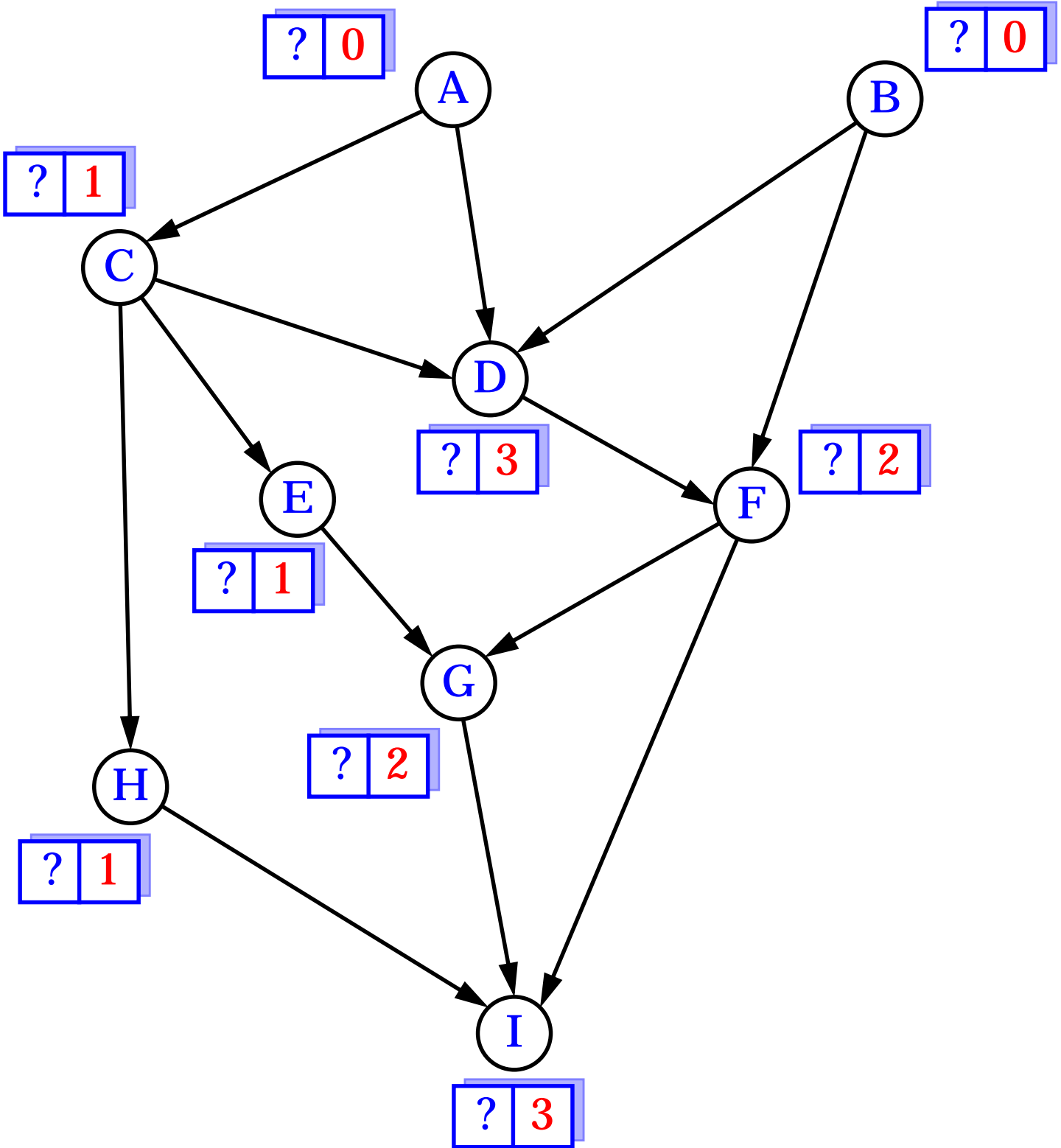
Algorithm (continued)

Simulate deletion of sources using indegree counters

```
TopSort(Vertex v);  
  label v;  
  foreach edge(v,w)  
    indeg(w) = indeg(w) - 1;  
    if indeg(w) = 0  
      TopSort(w);
```

1. Compute $\text{indeg}(\mathbf{v})$ for all vertices
2. Foreach vertex \mathbf{v} do
 if \mathbf{v} not labeled and $\text{indeg}(\mathbf{v}) = 0$
 then **TopSort**(\mathbf{v})

Example



Reverse Topological Sorting

```
RevTopSort(Vertex v)
  mark v;
  foreach edge(v,w)
    if v not marked
      RevTopSort(w);
  label v;
```

