Time-Optimized Task Offloading Decision Making in Mobile Edge Computing

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Second UK Mobile, Wearable and Ubiquitous Systems Research Symposium 1st-2nd July 2019, Dept of Computer Science, University of Oxford, UK





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Outline



- Background
- Occupation Task Offloading
- Previous Work
- System Model & Problem Statement
- Optimal Stopping Theory
- O Performance Evaluation
 - Data Sets
 - Performance Metrics & Assessment
- Onclusions

Background¹



- The recent advances in mobile devices
 - Example
 - Limitation
- Mobile Cloud Computing (MCC)
 - What is MCC?
 - Limitation
- Mobile Edge Computing (MEC)
 - What is MEC?
 - Names
 - ★ iCloud
 - ★ Fog Computing
 - ★ Mobile Edge Computing
 - Use cases

Computation Offloading



- Dispatching intensive tasks to an external server, i.e., Cloud or an Edge server.²
 - Face/speech recognition;
 - Augmented, assisted or virtual reality;
 - Low latency applications, such as online gaming or remote desktop;
 - Big data analytic.
- The authors³ demonstrated on a real MEC testbed that the reduction of **latency** up to 88% and **energy consumption** of the mobile device up to 93% can be accomplished by the computation/task offloading in MEC.

²Pavel Mach and Zdenek Becvar. "Mobile edge computing: A survey on architecture and computation offloading". In: IEEE Communications Surveys & Tutorials 19.3 (2017), pp. 1628–1656.





• Offloading Sequential Decision Making

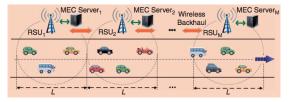
- Doing the tasks either locally or offloading them
- Locally, Cloud, or at the Edge
- Which Edge server to offload?

⁴Pavel Mach and Zdenek Becvar. "Mobile edge computing: A survey on architecture and computation offloading". In: IEEE Communications Surveys & Tutorials 19.3 (2017), pp. 1628–1656. イロト イロト イロト イロト マロト マロト

Previous Work



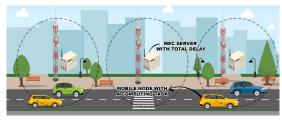
- Different from previous work, we focus on the **decision of when** to offload to an edge server, i.e., the selection of MEC servers/time.
- ST-CODA⁵: A spatial and temporal computation offloading decision algorithm.
- A predictive off-loading framework in vehicular networks.⁶



⁵Haneul Ko, Jaewook Lee, and Sangheon Pack. "Spatial and Temporal Computation Offloading Decision Algorithm in Edge Cloud-Enabled Heterogeneous Networks". In: *IEEE Access* 6 (2018), pp. 18920–18932.

System Model

- Mobile device
- MEC server
- Computing task with total delay D such that:
 - D_{offload} < D_{local}
- *D_{offload}* delay includes:
 - Transmission Time;
 - Processing Time;
 - Time spent to receive the processed data from MEC server to mobile device.





Problem Statement



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The mobile node should find the best time instance t^* such that the expected total delay $\mathbb{E}[D]$ for the offloading is minimized, i.e., the optimal stopping time t^* achieves the essential infimum:

$$\operatorname{ess\,inf}_{t} \mathbb{E}[D_{t}] \tag{1}$$

This problem is a sequential decision making solved based on the principles of the Optimal Stopping Theory (OST).

Optimal Stopping Theory



- Concerned with the problem of choosing the **best time instance** to take a given action based on sequentially observed random variables in order to minimize an expected cost.
- In our problem, we have two actions: offload or continue observing.
- We have two states: the user has offloaded the data, or still looking for a MEC server.
- **Abstraction**: we cast our offloading problem as a finite horizon OST problem, in which we know the upper bound *n*, i.e., the number of stages at which one may stop⁷.

⁷Ke Zhang et al. "Mobile-edge computing for vehicular networks: A promising network paradigm with predictive off-loading". In: *IEEE Vehicular Technology Magazine* 12.2 (2017), pp. 36–44.

Optimal Offloading Rule



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- We provide an **estimate** of the optimal offloading time.
- The optimal offloading time is determined by the scalar values a_1, a_2, \ldots, a_n through which the mobile node decides either to offload or not:

Optimal Task Offloading Rule

Offload the data at the k-th MEC server if $D_k \leq a_k$; otherwise continue the observation if $D_k > a_k$.

Cont'd



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Problem: Estimation of the scalar variable $\{a_k\}$.

The scalar variable *a* values are calculated once through *backward induction*.

$$a_{k} = \frac{1}{1+r} \left(a_{k+1} (1 - F_{D}(a_{k+1})) + \int_{0}^{a_{k+1}} u dF_{D}(u) \right)$$
(2)

$$a_n = \frac{1}{1+r} \int_0^1 u dF_D(u) = \frac{1}{1+r} \mathbb{E}[D], \qquad (3)$$

 $F_D(u) = P(D \le u)$ is the cumulative distribution function of the total delay D.

From Model to Algorithm



Input: Decision scalar values $a_1, a_2, ..., a_n$ **Output:** Decision of which MEC server to offload

```
Offload \leftarrow FALSE
for k = 1 \cdot n do
  if current total delay D_k \leq a_k then
     MEC-Server \leftarrow k:
     Offload \leftarrow TRUE; break;
  end if
end for
if Offload == FALSE then
  MEC-Server \leftarrow n:
end if
Offload tasks/data to the MEC-Server;
```

Experiment: Data Set



- We used the real dataset of taxi cabs' movements in Rome⁸.
- The dataset contains GPS coordinates of 320 taxis collected over 30 days.
- For each movement, the mobile node is observing a server to check the the expected delay *D*.

Car id	Time	lat	long	Delay	Server
156	"2014-02-0100:00:00.73"	41.88	12.48	80.61	4
156	"2014-02-0100:00:16.47"	41.88	12.48	62.97	4
156	"2014-02-0100:00:30.70"	41.88	12.48	4.53	4
156	"2014-02-0100:00:45.30"	41.88	12.49	4.37	4
187	"2014-02-0100:00:01.14"	41.92	12.46	70.17	1
187	"2014-02-0100:00:16.15"	41.92	12.46	66.59	1
187	"2014-02-0100:00:30.81"	41.92	12.47	31.65	4

 ⁸Lorenzo Bracciale et al. CRAWDAD dataset roma/taxi (v. 2014-07-17).

 Downloaded from https://crawdad.org/roma/taxi/20140717. July 2014. DOI:

 10.15783/C7QC7M.

Evaluation



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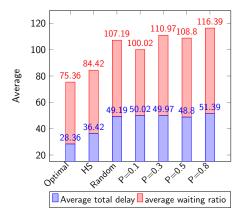


Figure: Average total delay and average waiting ratio of all models

Future Work and Conclusions



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• We aim to consider the case where the number of the servers (times) is **unknown and not provided** to the mobile nodes.



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Thank you! Contact: Ibrahim Alghamdi Email address: i.alghamdi.1@research.gla.ac.uk