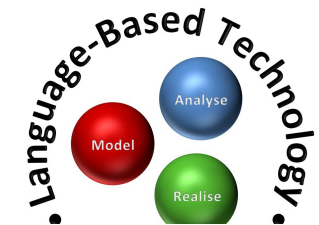


Discretionary Information Flow Control for Interaction-Oriented Specifications

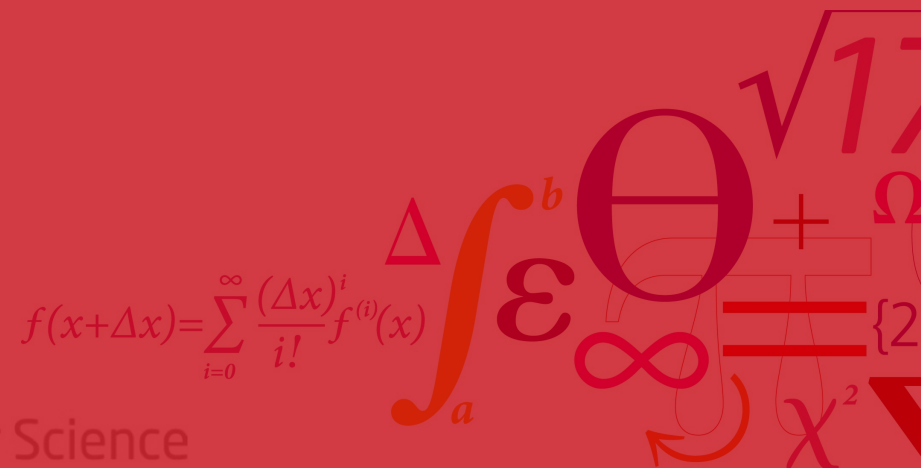
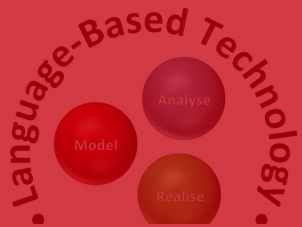
Alberto Lluch Lafuente, Flemming Nielson, Hanne Riis-Nielson



$$f(x+\Delta x) = \sum_{i=0}^{\infty} \frac{(\Delta x)^i}{i!} f^{(i)}(x)$$

$$\int_a^b \epsilon \Theta \sqrt{1+\Omega} + \chi^2$$

MOTIVATIONS



HACKERS COULD COMMANDEER NEW PLANES THROUGH PASSENGER WI-FI



An Airbus A350 on an assembly line, in Toulouse, France, April 11, 2015.  REMY

GABALDA/AFP/GETTY

HACKERS COULD COMMANDEER NEW PLANES THROUGH PASSENGER WI-FI

Some activities at DTU/LBT

Adapting DLM for dealing Airbus needs.


Information flow control challenges:

- Onboard inter-domain gateways;
- data-dependent routing.

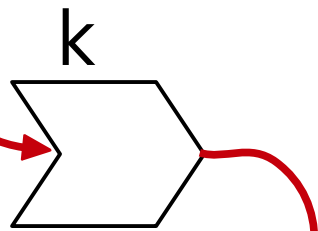
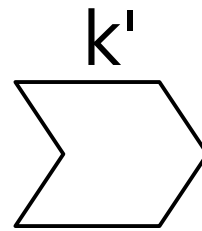
Approach:

- combine DLM with Hoare Logics;
- DLM model that can deal with the Airbus gateway.



An Airbus A350 on an assembly line, in Toulouse, France, April 11, 2015.  REMY

channels



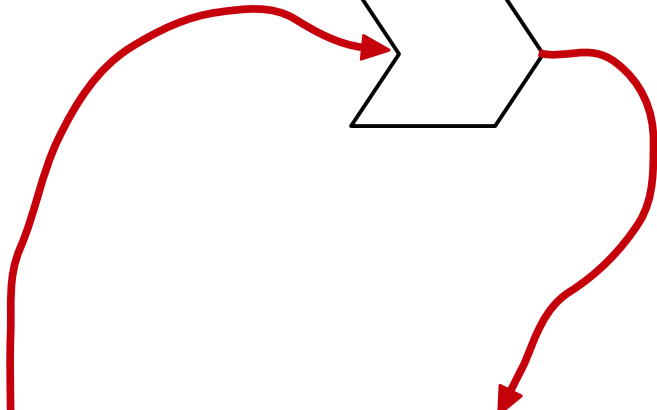
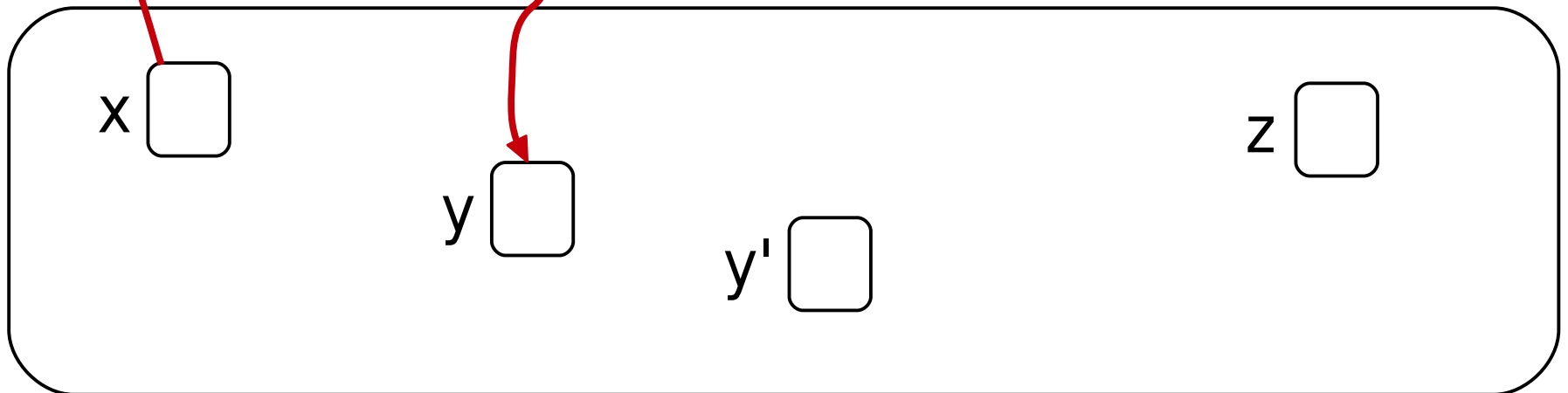
processes

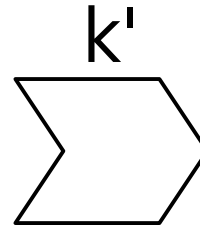
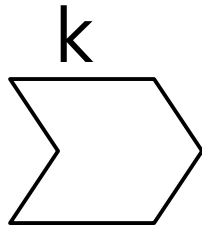
$[k!x]_p$

$[k?y ; k'!a ; k!y']_q$

$[k'?z ; k?z]_r$

memory





channels

processes

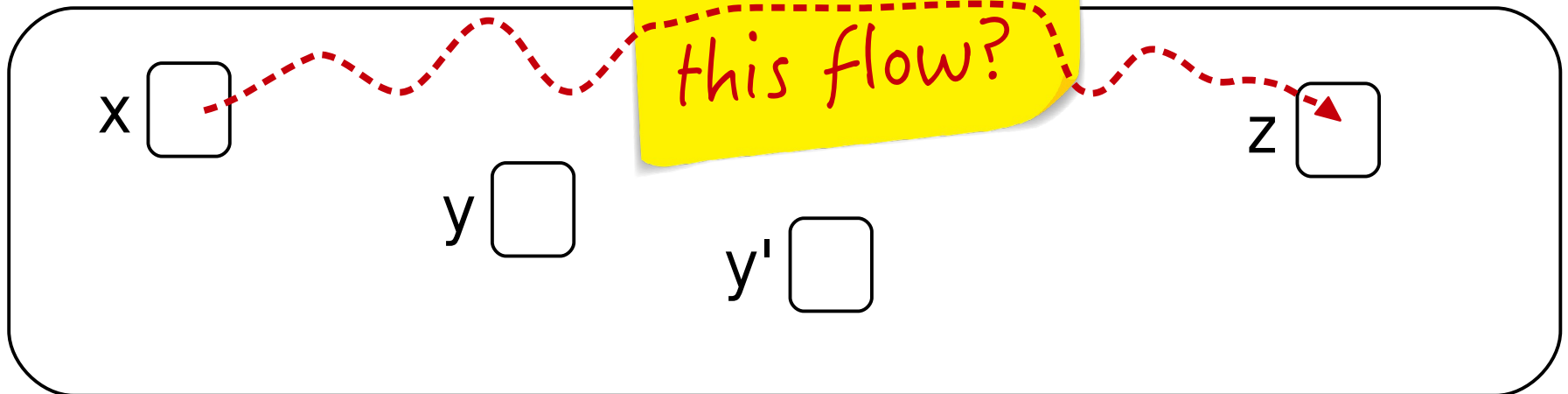
$[k!x]_p$

$[k?y ; k'!a ; k!y']_q$

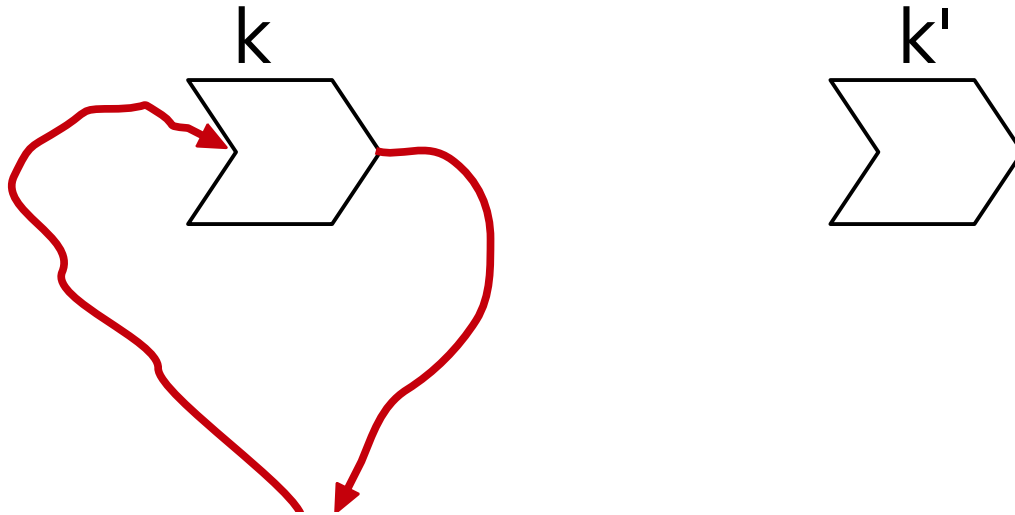
$[k'?z ; k?z]_r$

do we have
this flow?

memory



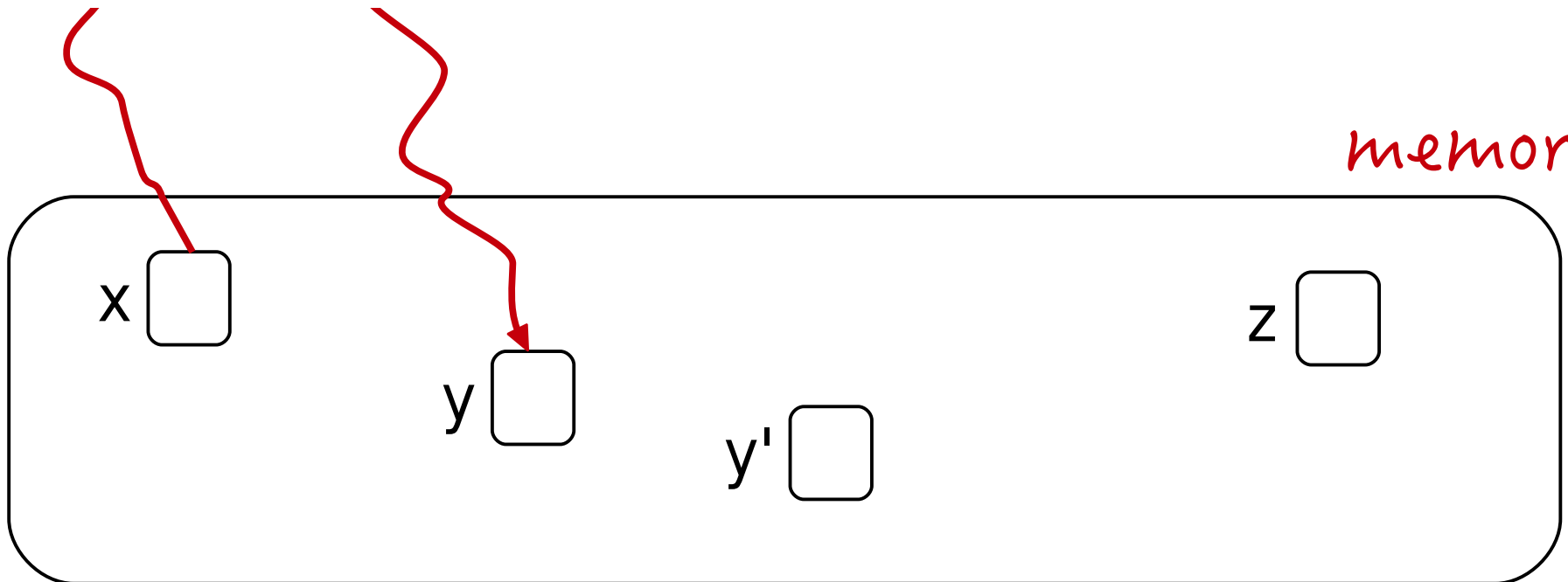
channels

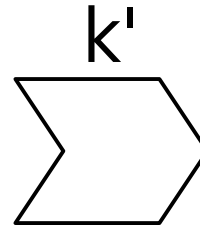
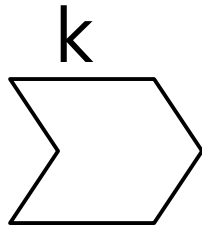


processes

$p.x \rightarrow q.y : k ; q.a \rightarrow r.z : k' ; q.y' \rightarrow r.z : k$

memory

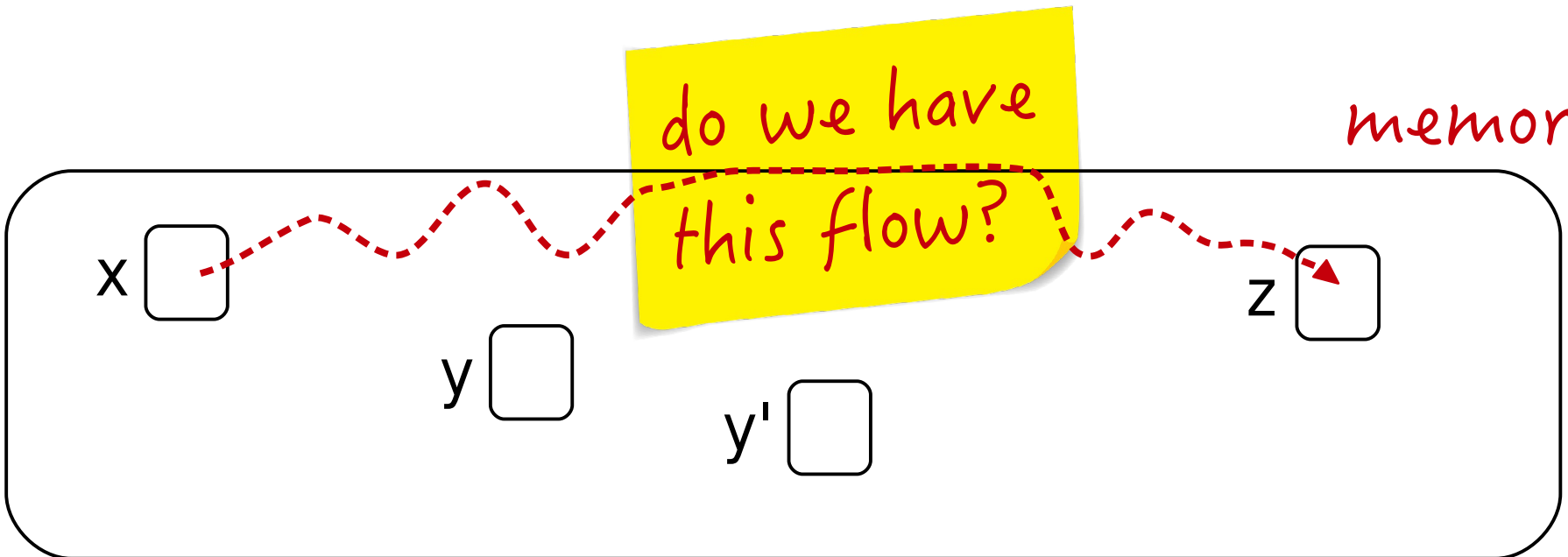




channels

processes

$p.x \rightarrow q.y : k ; q.a \rightarrow r.z : k' ; q.y' \rightarrow r.z : k$



typical service/protocols choreographies

<pre> u.name -> rp.user : a ; rp.user -> ip.id : b ; u.my_pwd -> ip.pwd : a ; if check(id,pwd)@ip then ip."ok" -> rp."ok" : b ; rp.class(user) -> s.class : c else ip."fail" -> rp."fail" : b ; rp."na" -> s.class : c ; (ip.rep(id) -> rp.report : b (data := first(class) @ s; while data ≠ nil @s do s.data -> u.info : a ; data := data.next @ s then s."end" -> u.info : a)) </pre>	$\left[\begin{array}{l} a!name ; \\ a!my_pwd ; \\ \text{loop} \\ \quad a?info \\ \quad \oplus (a?"end" ; \\ \quad \quad \text{break}) \end{array} \right]_u$	$\left[\begin{array}{l} b?id ; \\ a?pwd ; \\ \text{if check(id,pwd) then} \\ \quad b!"ok" \\ \text{else} \\ \quad b!"fail" ; \\ b!rep(id) ; \end{array} \right]_{ip}$
<pre> (ip.rep(id) -> rp.report : b (data := first(class) @ s; while data ≠ nil @s do s.data -> u.info : a ; data := data.next @ s then s."end" -> u.info : a)) </pre>	$\left[\begin{array}{l} a?user ; \\ b!user ; \\ ((b?"ok" ; \\ \quad c!class(user)) \\ \quad \oplus (b?"fail") \\ \quad \quad c!"na") ; \\ b?report ; \end{array} \right]_{rp}$	$\left[\begin{array}{l} c?class ; \\ \text{data := first(class) ;} \\ \text{while data ≠ nil then} \\ \quad a!data ; \\ \quad \text{data := data.next ;} \\ \text{then} \\ \quad a!"end" ; \end{array} \right]_s$

HPC choreographies?

A.x2 -> B.y : k;

(

x1 := f(x1) @ A | y := f(y) @ B

);

B:y -> A.x2 : k;

z := aggregate(x1,x2) @ A;

map-reduce (2 processes)

A1 -> A2 : k2 ; A1 -> A3 : k3;

(

x1 := f(x1) @ A1 | x2 := f(x2) @ A2 | x3 := f(x3) @ A3

);

A2 -> A1 : k2;

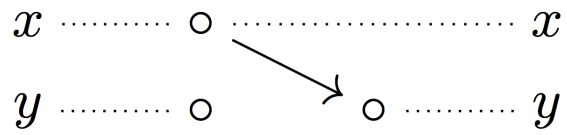
A3 -> A1 : k3;

z := aggregate(x1,x2,x3) @ A1;

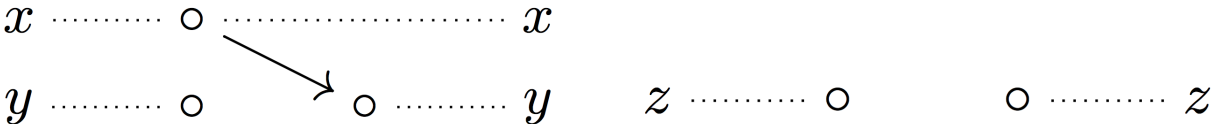
map-reduce (3 processes)

$p.x \rightarrow q.y : k ; q.a \rightarrow r.z : k' ; q.y' \rightarrow r.z : k$

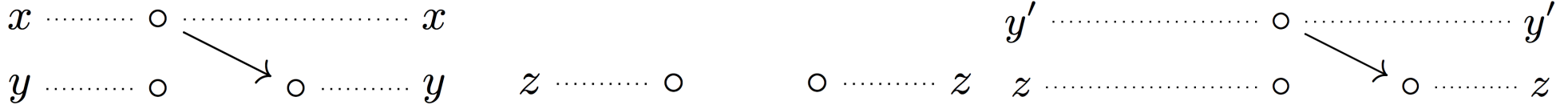
$p.x \rightarrow q.y : k ; q.a \rightarrow r.z : k' ; q.y' \rightarrow r.z : k$



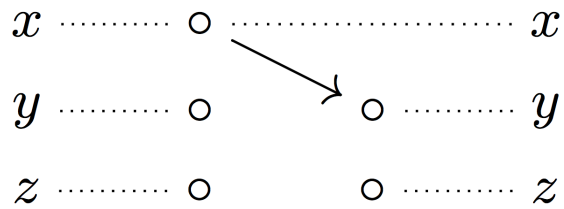
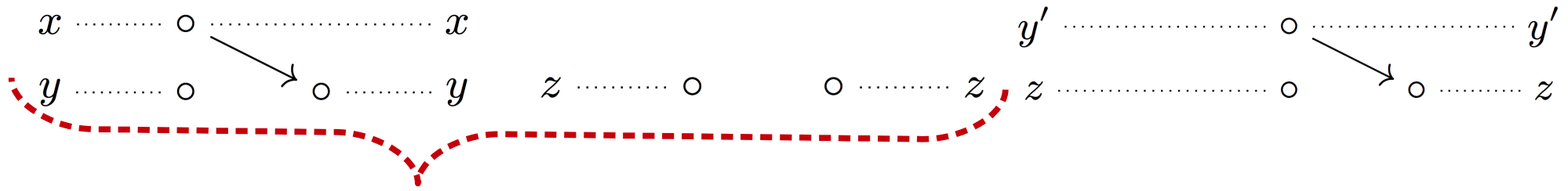
$p.x \rightarrow q.y : k ; q.a \rightarrow r.z : k' ; q.y' \rightarrow r.z : k$



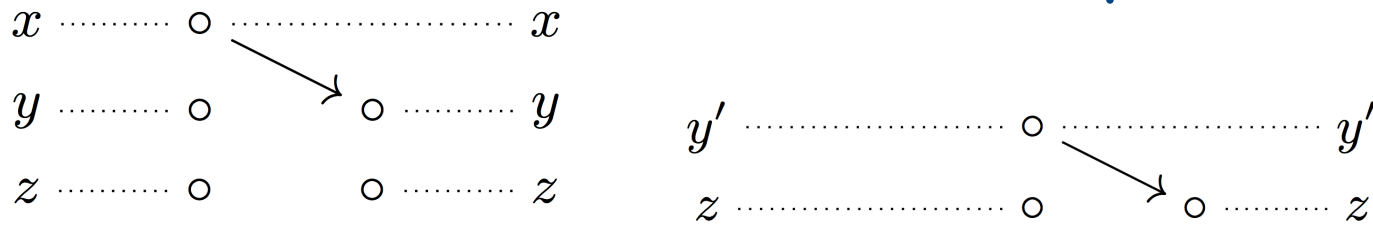
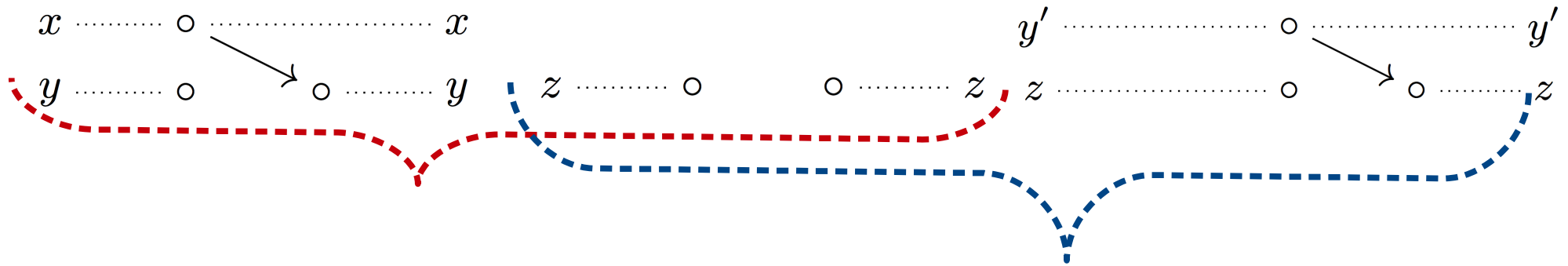
$p.x \rightarrow q.y : k ; q.a \rightarrow r.z : k' ; q.y' \rightarrow r.z : k$



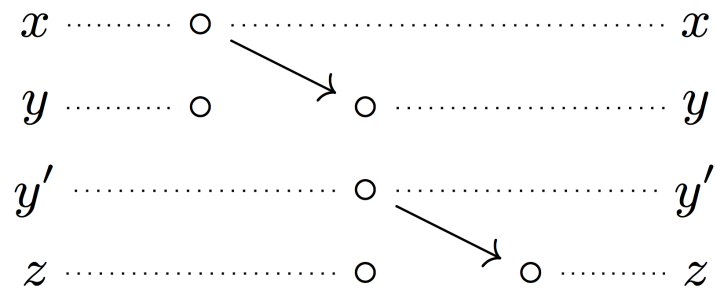
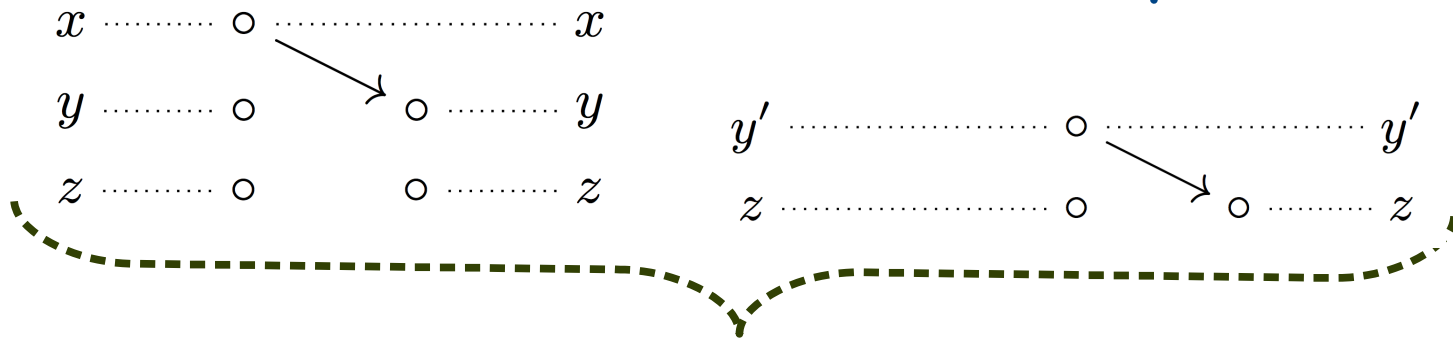
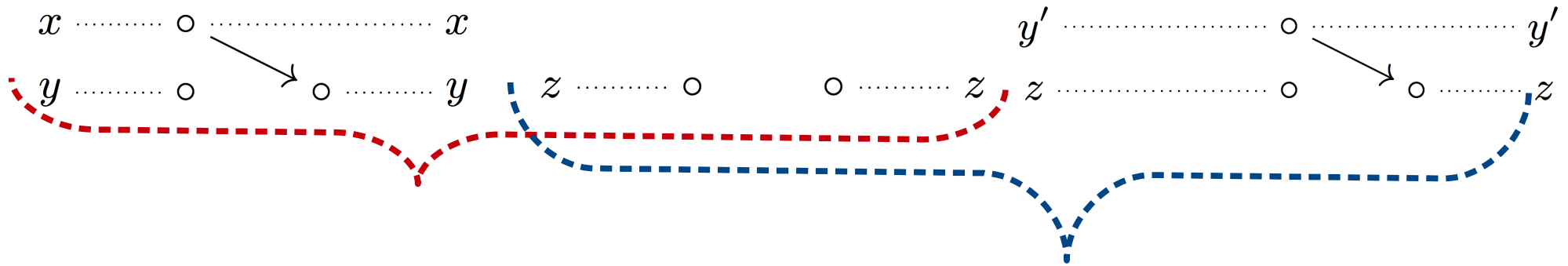
$p.x \rightarrow q.y : k ; q.a \rightarrow r.z : k' ; q.y' \rightarrow r.z : k$



$p.x \rightarrow q.y : k ; q.a \rightarrow r.z : k' ; q.y' \rightarrow r.z : k$

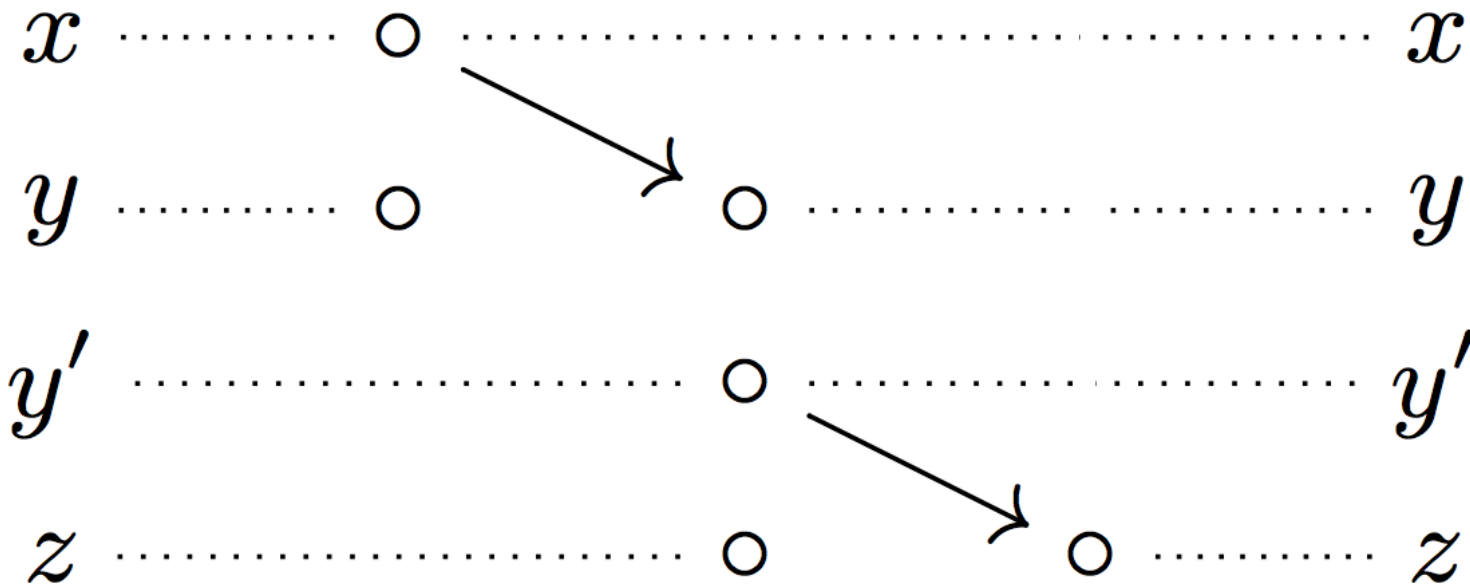


$p.x \rightarrow q.y : k ; q.a \rightarrow r.z : k' ; q.y' \rightarrow r.z : k$



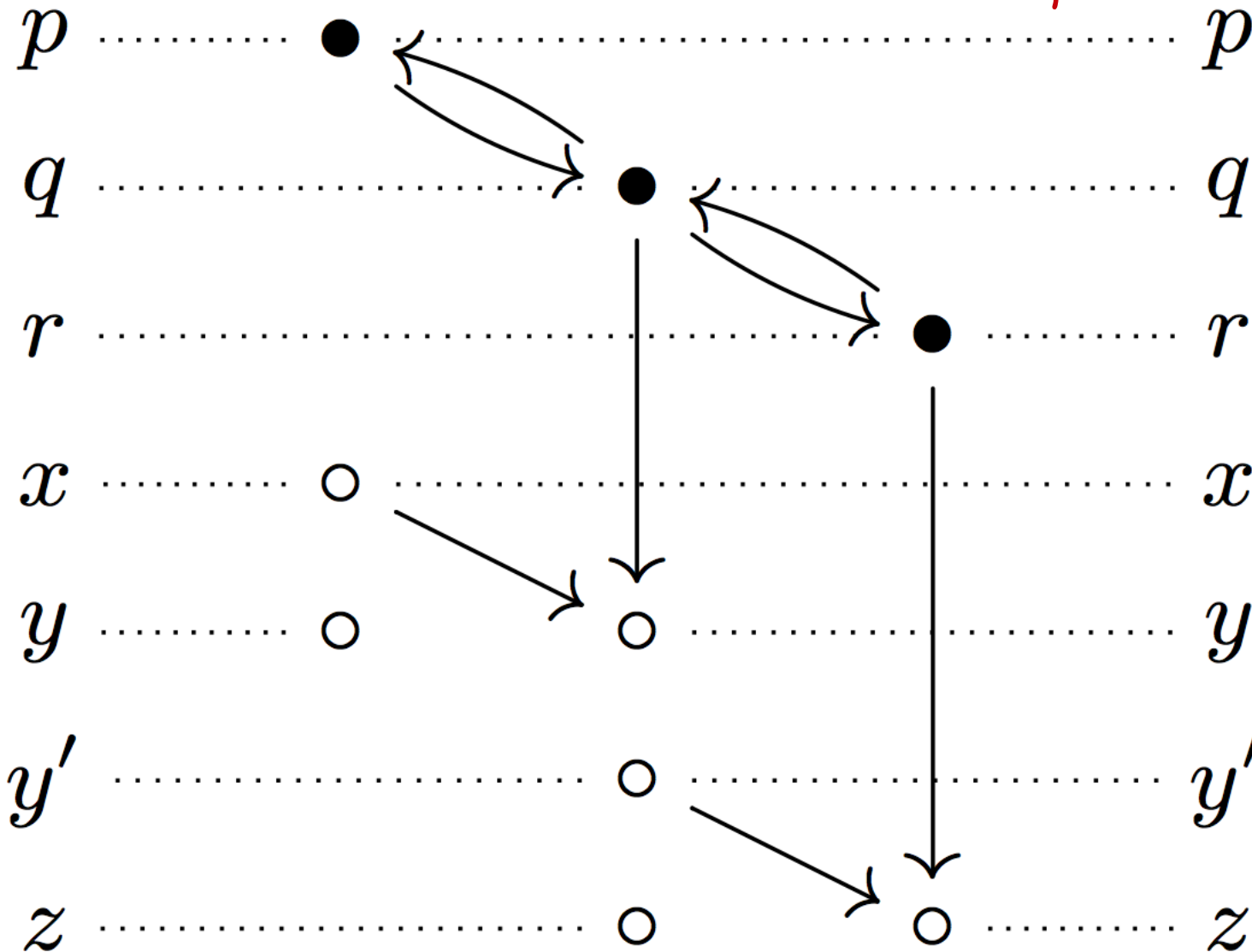
$p.x \rightarrow q.y : k ; q.a \rightarrow r.z : k' ; q.y' \rightarrow r.z : k$

Explicit dataflow

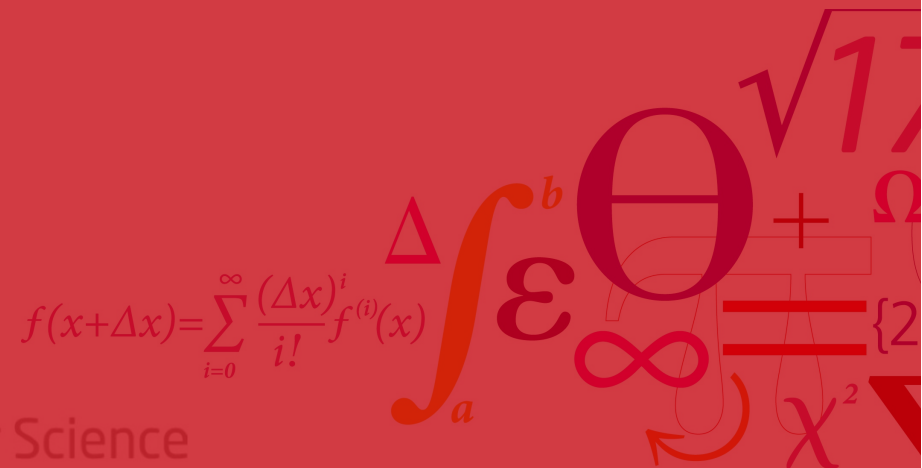
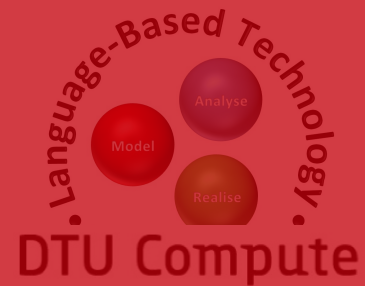


$p.x \rightarrow q.y : k ; q.a \rightarrow r.z : k' ; q.y' \rightarrow r.z : k$

"some" implicit dataflow



INTERACTION-ORIENTED CHOREOGRAPHIES



Trace-based semantics

$$\text{Traces}(C_1; C_2) = \text{Traces}(C_1) \text{Traces}(C_2)$$

$$\text{Traces}(C_1 \mid C_2) = \text{Traces}(C_1) \bowtie \text{Traces}(C_2)$$

$$\text{Traces}(\text{if } e @ p \text{ then } C_1 \text{ else } C_2) = e @ p (\text{Traces}(C_1) \cup \text{Traces}(C_2))$$

$$\text{Traces}(\text{while } e @ p \text{ do } C_1 \text{ then } C_2) = e @ p (\text{Traces}(C_1) e @ p)^* \text{Traces}(C_2)$$

$$\text{Traces}(A) = \{A\}$$

$$\text{Traces} : \mathcal{C} \rightarrow 2^{\mathcal{A}^*}$$

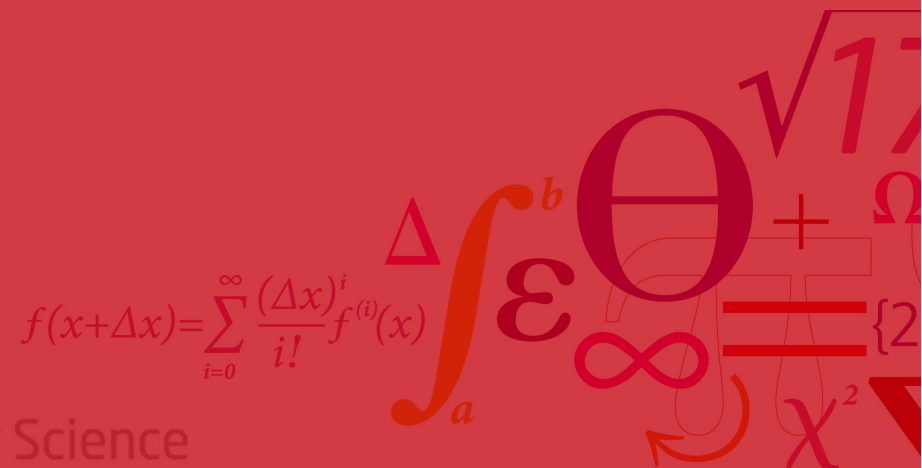
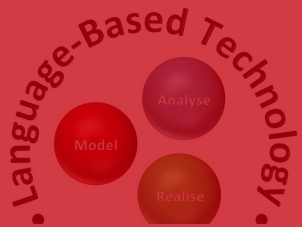
$$\mathcal{A} = \mathcal{A} \cup \{e @ p \mid e \in \mathbf{Expr}, p \in \mathbf{Prin}\}$$

Well-formedness criteria for choreographies

C is *well-formed* if

1. every occurrence of $C_1 \mid C_2$ in C should be such that
 $en(C_1) \cap en(C_2) = \emptyset$;
2. all traces $\sigma \in Traces(C)$ satisfy the following condition:
If $\sigma = \sigma' \alpha \beta \sigma''$, with $\alpha, \beta \in \mathcal{A}$ then
 $pn(\alpha) \cap pn(\beta) \neq \emptyset$
or
 $\sigma' \beta \alpha \sigma'' \in Traces(C)$.

INFORMATION FLOWS



Graph-based flows and their composition

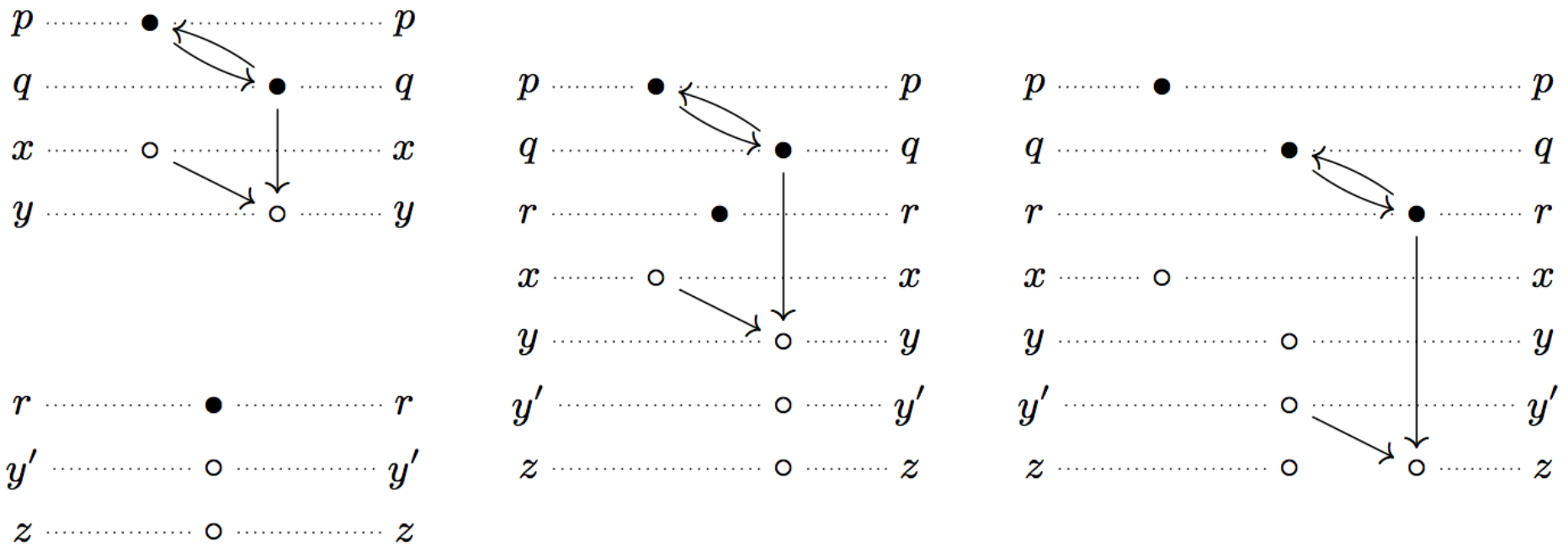
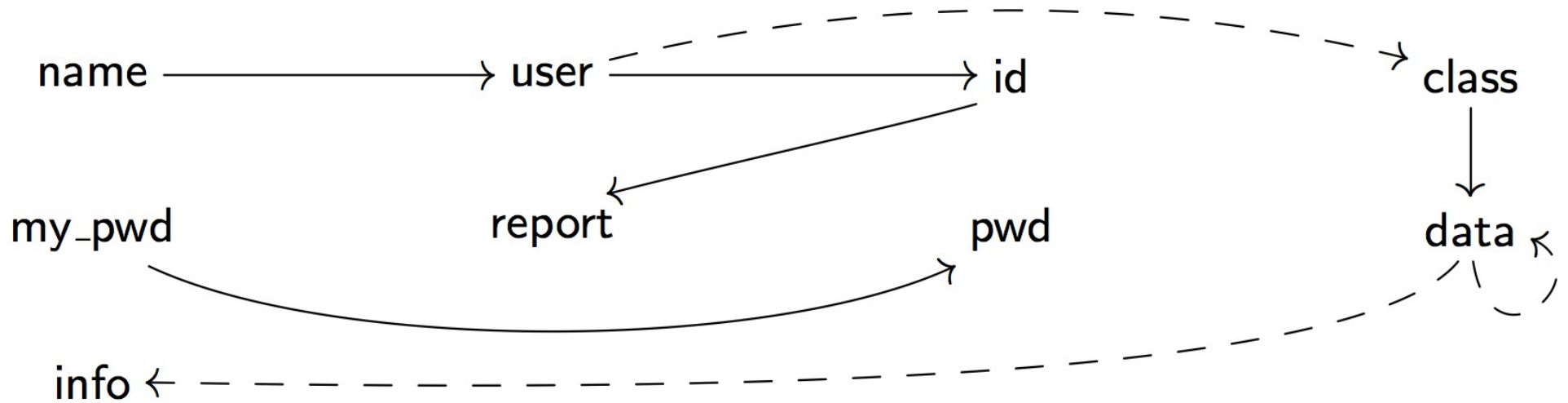


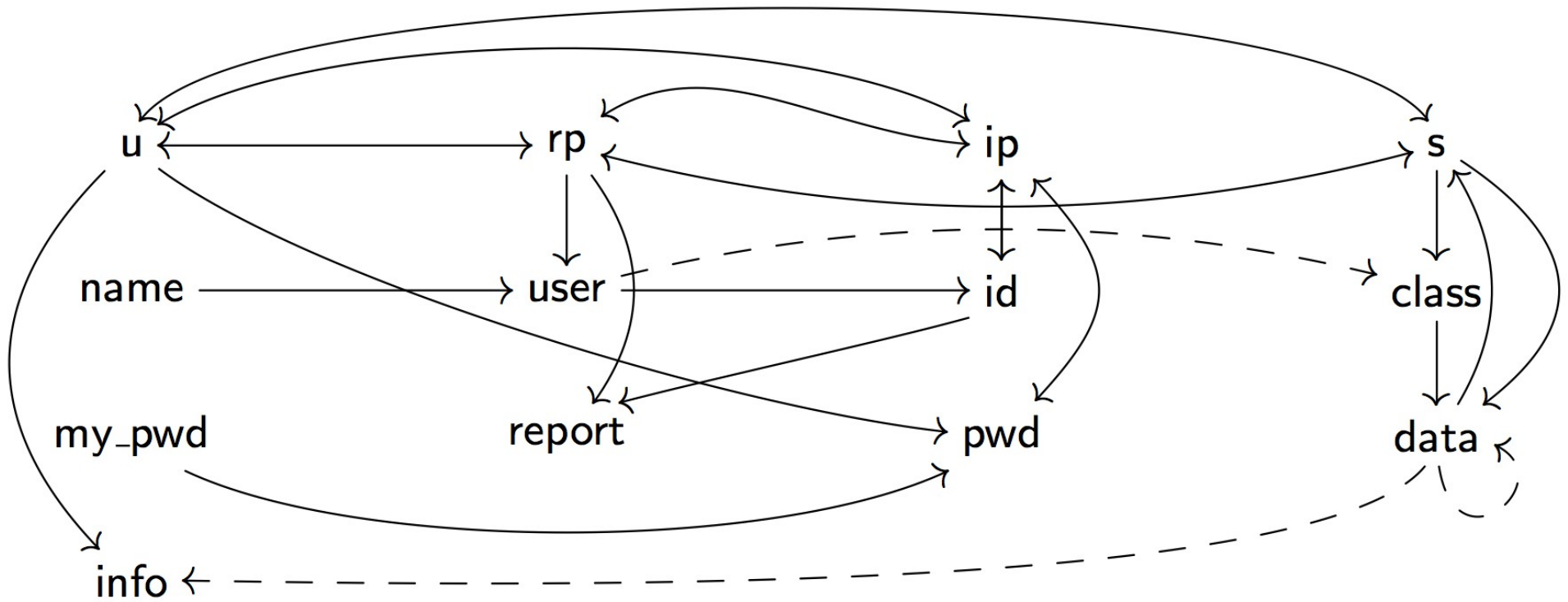
Fig. 5. Flows F_1 (top left), $\text{Id}_{\{r, y', z\}}$ (bottom left), $F_1 \otimes \text{Id}_{\{r, y', z\}}$ (mid) and F_2 (right).

flow graphs as terms, e.g. $(F_1 \otimes \text{Id}_{\{r, y', z\}}) \circ F_2$

A big (policy) flow graph (simplified)



A big (policy) flow graph (simplified)

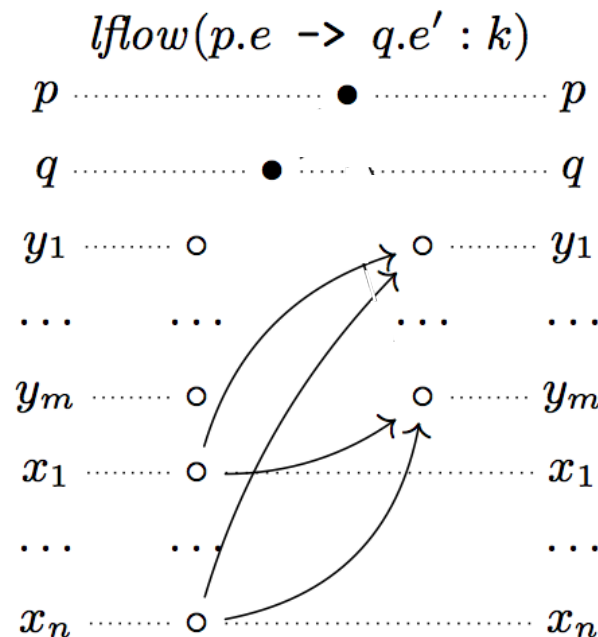
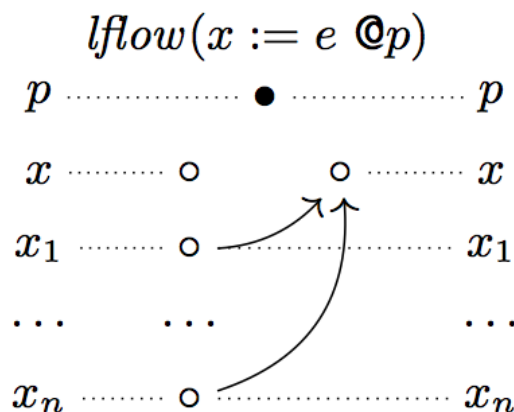
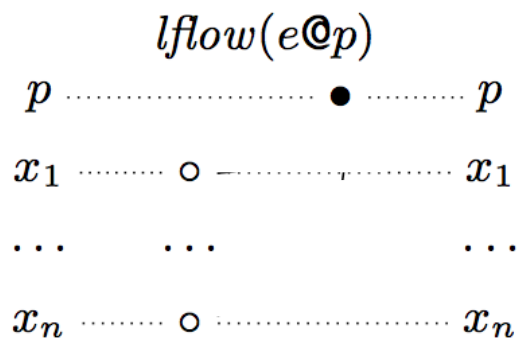


Examples of flow annotations (i)

- explicit data flows only -

$$flow(\alpha) = lflow(\alpha) \otimes \mathbf{I}_{\mathbf{Ent} \setminus en(\alpha)}$$

$$lflow(\text{skip}) = \mathbf{0}$$



$$fn(e) = \{x_1, \dots, x_n\}$$

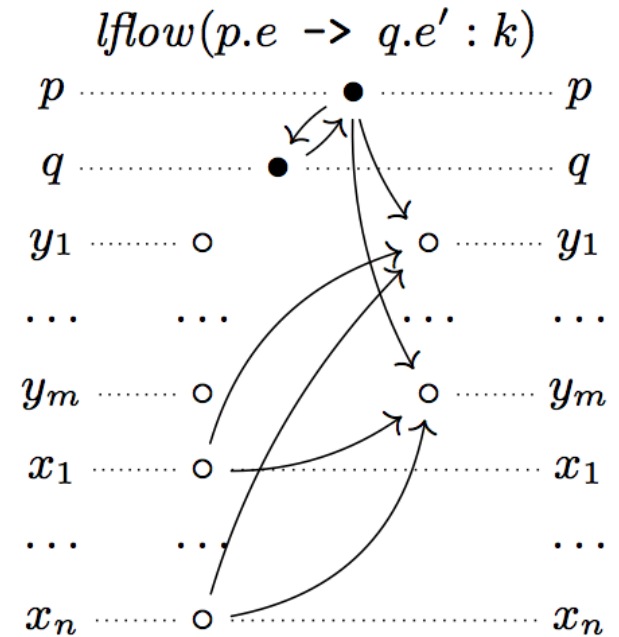
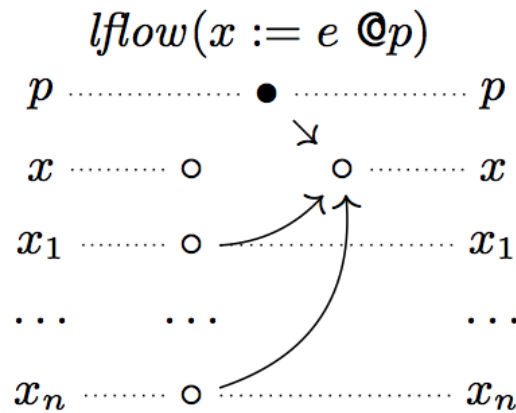
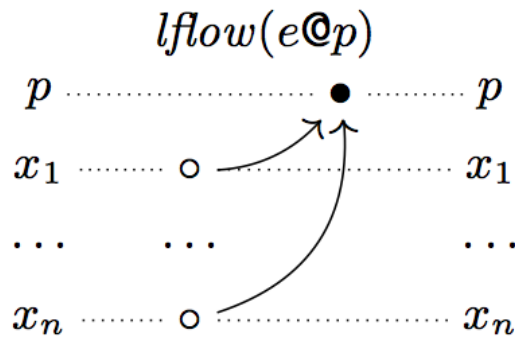
$$fn(e') = \{y_1, \dots, y_m\}$$

Examples of flow annotations (ii)

- some implicit flows included -

$$flow(\alpha) = lflow(\alpha) \otimes \mathbf{I}_{\mathbf{Ent} \setminus en(\alpha)}$$

$$lflow(\text{skip}) = \mathbf{0}$$



$$fn(e) = \{x_1, \dots, x_n\}$$

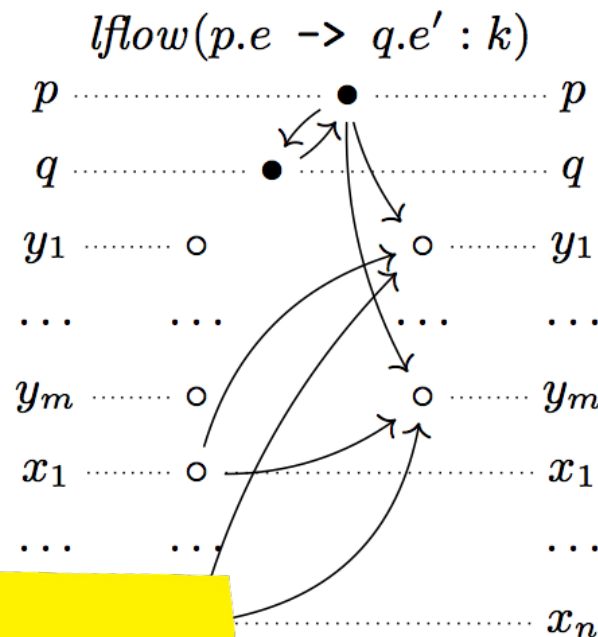
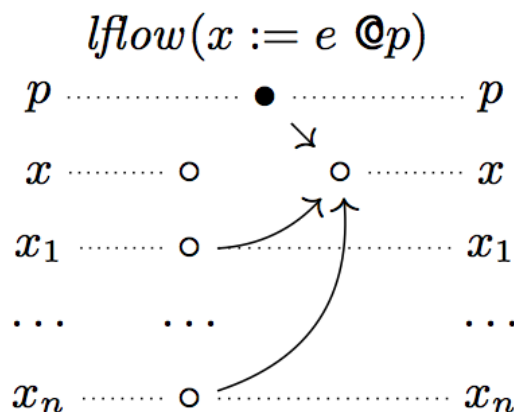
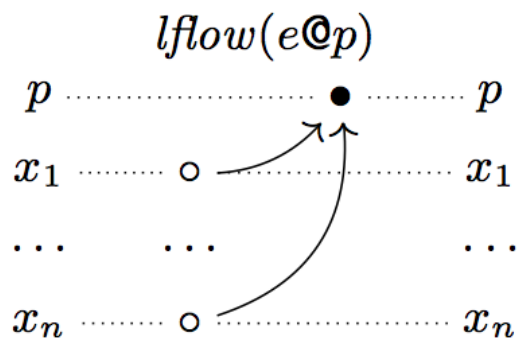
$$fn(e') = \{y_1, \dots, y_m\}$$

Examples of flow annotations (ii)

- implicit flows included -

$$flow(\alpha) = lflow(\alpha) \otimes \mathbf{I}_{\mathbf{Ent} \setminus en(\alpha)}$$

$$lflow(\text{skip}) = \mathbf{0}$$



Well-formed annotations

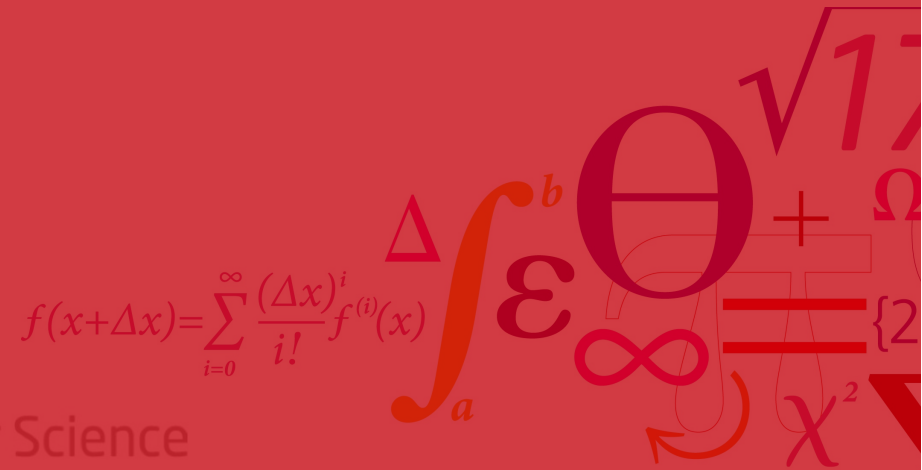
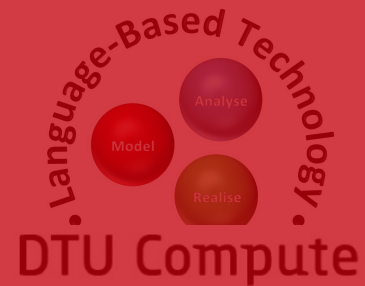
$flows : \mathcal{A} \rightarrow \mathcal{F}$ is well-formed iff

$$\forall \alpha \in \mathcal{A} : flows(\alpha) = F \otimes \mathbf{I}_{\mathbf{Ent} \setminus en(F)} \wedge en(F) \subseteq en(\alpha)$$

$$fn(e) = \{x_1, \dots, x_n\}$$

$$fn(e') = \{y_1, \dots, y_m\}$$

CHECKING INFORMATION FLOW POLICIES



When is a policy satisfied?

$C \models \Pi$ iff $Traces(C) \models \Pi$

$T \models \Pi$ iff $\forall \sigma \in T : \sigma \models \Pi$

$\sigma \models \Pi$ iff $\sigma = \sigma''\sigma'\sigma''' \Rightarrow \sigma' \vdash \Pi$

$\sigma \vdash \Pi$ iff $flows(\sigma) \models \Pi$

$F \models \Pi$ iff $\forall \eta, \eta' \in en(\Pi) :$

$$i_F(\eta) \rightarrow_{G_F}^* o_F(\eta') \Rightarrow i_\Pi(\eta) \rightarrow_{G_\Pi}^* o_\Pi(\eta')$$

In words: no sub-trace can have a flow not allowed by the policy.

Checking types/policies

$$\frac{\text{en}(\text{Ent}) \vdash C_1 : \Pi \quad \vdash C_2 : \Pi}{\vdash C_1; C_2 : \Pi}$$

$$\frac{\vdash C_1 : \Pi \quad \vdash C_2 : \Pi}{\vdash C_1 \mid C_2 : \Pi}$$

$$\frac{A \models \Pi}{\vdash A : \Pi}$$

$$\frac{e@p \models \Pi \quad \vdash C_1 : \Pi \quad \vdash C_2 : \Pi}{\vdash \text{if } e@p \text{ then } C_1 \text{ else } C_2 : \Pi}$$

$$\frac{e@p \models \Pi \quad \vdash C_1 : \Pi \quad \vdash C_2 : \Pi}{\vdash \text{while } e@p \text{ do } C_1 \text{ then } C_2 : \Pi}$$

Main result

$$\vdash C : \Pi \text{ then } C \models \Pi$$

In practice: just check all actions and conditions.

inferring types/over-approximating flows

$$\text{en}(\text{Ent}) \frac{\vdash C_1 : F_1 \quad \vdash C_2 : F_2}{\vdash C_1; C_2 : F_1 \odot F_2} \quad \frac{\vdash C_1 : F_1 \quad \vdash C_2 : F_2}{\vdash C_1 \mid C_2 : F_1 \otimes F_2} \quad \frac{}{\vdash A : \text{flow}(F)}$$

$$\frac{\vdash C_1 : F_1 \quad \vdash C_2 : F_2}{\vdash \text{if } e@p \text{ then } C_1 \text{ else } C_2 : \text{flows}(e@p) \odot (F_1 \otimes F_2)}$$

$$\frac{\vdash C_1 : F_1 \quad \vdash C_2 : F_2}{\vdash \text{while } e@p \text{ do } C_1 \text{ then } C_2 : \text{flows}(e@p) \odot (F_1 \odot \text{flows}(e@p)^\infty \odot F_2)}$$

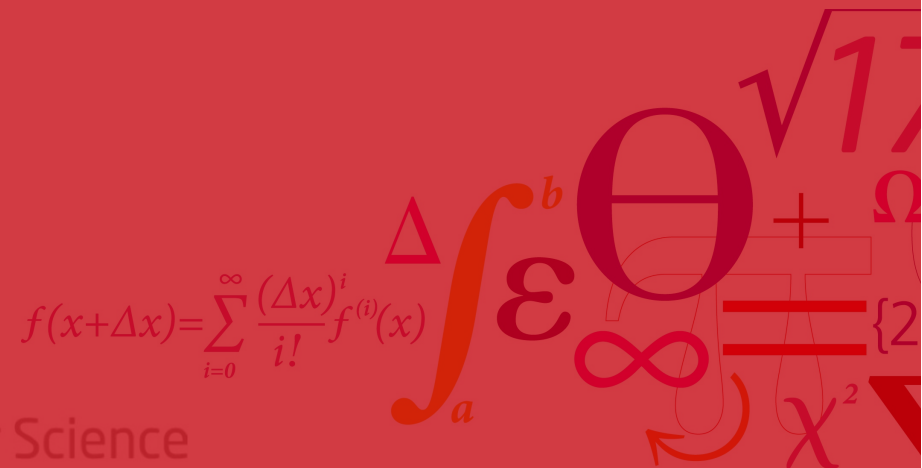
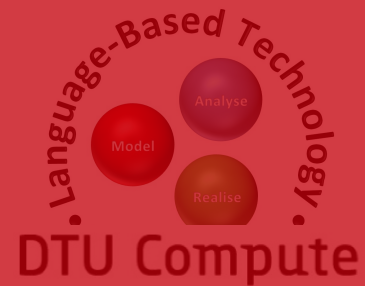
where $F \odot G = F \otimes G \otimes (F \circ G)$

Conjecture

$$\vdash C : F \text{ then } C \models F$$

$C \models \Pi$ could be checked by checking $F \models \Pi$

CONCLUDING REMARKS



Summary

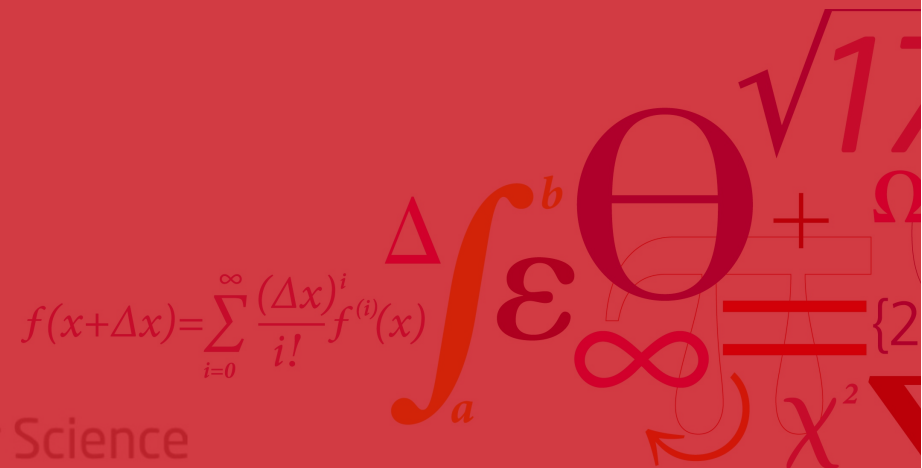
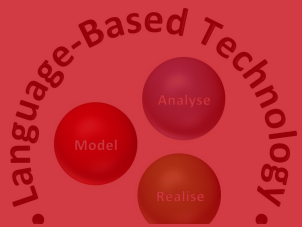
- 1 Simple choreography description language to provide **interaction-oriented** specifications of concurrent systems
- 2 Graph-based information flow specifications
 - (i) semantics (flow annotations for events)
 - (ii) policies
- 3 Sound type system based on over-approximation of the flows in a specification

Future work?

Some issues/extensions worth considering:

- Over- and Under-approximations
- Type inference
- Non-interference
- Intransitive policies
- Compositionality and Dynamicity
- HPC primitives (e.g. MPI-like scatter/agg.)
- Projections (distributed implementation)

THANKS!



Questions?

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