Review of the Bron-Kerbosch algorithm and variations

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Abstract

This report describes six different variations of the Bron-Kerbosh algorithm (which solves the problem of listing all maximal cliques in a graph) and compares their performance.
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Chapter 1

Introduction

The Bron-Kerbosch algorithm is used to find all maximal cliques in an undirected graph.

1.1 Implementation

The algorithms were implemented in Java, which is not a fast language since it runs on a virtual machine. On top of that memory consumption wasn’t optimized since at each step of the search new data structures are created for each recursive call. This makes these implementation not optimal for usage in a real scenario, though good enough for the purpose of this report, since the focus is on comparing the algorithms rather than speeding up the process. The different implementations are all extension of the same class, which gives the basic structure of the execution. This guarantees that differences in the performance are due to the algorithms themselves rather than differences in the implementation.
Chapter 2

The algorithms

2.1 Classic Bron-Kerbosch

This is a simple implementation of the Bron-Kerbosch algorithm.

**Algorithm 1: Classic Bron-Kerbosch algorithm**

\[
\text{BronKerbosch}(R, P, X) \\
1 \quad \text{if } P \text{ and } X \text{ are both empty then} \\
2 \quad \text{report } R \text{ as a maximal clique} \\
3 \quad \text{for each vertex } v \text{ in } P \text{ do} \\
4 \quad \quad \text{BronKerbosch}(R \cup v, P \cap N(v), X \cap N(v)) \\
5 \quad P \leftarrow P \setminus v \\
6 \quad X \leftarrow X \cup v
\]

On the first call \( R \) and \( X \) are set to \( \emptyset \), and \( P \) contains all the vertexes the graph. \( R \) is the temporary result, \( P \) the set of the possible candidates and \( X \) the excluded set. \( N(v) \) indicates the neighbors of the vertex \( v \).

The algorithm can be textualized as following: Pick a vertex \( v \) from \( P \) to expand. Add \( v \) to \( R \) and remove its non-neighbors from \( P \) and \( X \). Then pick another vertex from the new \( P \) set and repeat the process. Continue until \( P \) is empty. Once \( P \) is empty, if \( X \) is empty then report the content of \( R \) as a new maximal clique (if it’s not then \( R \) contains a subset of an already found clique). Now backtrack to the last vertex picked and restore \( P, R \) and \( X \) as they were before the choice, remove the vertex from \( P \) and add it to \( X \), then expand the next vertex. If there are no more vertexes in \( P \) then backtrack to the superior level.

2.2 Bron-Kerbosch with degeneracy ordering

This algorithm is very similar to the classic Bron-Kerbosch. The difference is that on the outermost level of recursion the vertexes are picked in a specific order, called degeneracyordering. Given \( d \), degeneracy of the graph a degeneracyordering of the graph is an ordering in which each vertex has \( d \) or less neighbors which follow it in the ordering (it doesn’t matter how many neighbors precede it). A degeneracy ordering of a graph can be computed in linear time, so computing it doesn’t impact the computational complexity of the classic Bron-Kerbosh (which is exponential on the number of vertexes in the graph). David Eppstain demonstrated that a modified version of the Bron-Kerbosch that visits the graph using a degeneracyordering can be bound
in complexity to $O(d \times n \times 3^{d/3})$ (exponential on $d$), instead of the classic Bron-Kerbosch bound ($O(3^{n/3})$, exponential on $n$). This algorithm however, is not the one created by Eppstein et al.; as said before it is a classic Bron-Kerbosch with a modified outermost level of recursion. This was made to test how the ordering itself affects the execution of the algorithm.

### 2.3 Tomita

**Algorithm 2: Tomita et al.**

```
Tomita(R, P, X)
1 if P and X are both empty then
2     report R as a maximal clique
3 choose the pivot vertex $u$ in $P \cup X$ as the vertex with the highest number of neighbors in $P$
4 for each vertex $v$ in $P \setminus N(u)$ do
5     Tomita($R \cup v, P \cap N(v), X \cap N(v)$)
6     $P \leftarrow P \setminus v$
7     $X \leftarrow X \cup v$
```

Tomita is a modified version of the Bron-Kerbosch algorithm developed by Tomita et al. It uses a specific pivoting policy to cut computational branches. The pivoting consists in the following: instead of iterating at each expansion on the $P$ set, chose a pivot. The results will have to contain either the pivot or one of its non-neighbors, since if none of the non-neighbors of the pivot is included, then we can add the pivot itself to the result. Hence we can avoid iterating on the neighbors of the pivot at this step (they will still be expanded in the inner levels of recursion). The strategy proposed by Tomita et al. is to chose the pivot as the node in $P \cup X$ with the highest number of neighbors in $P$.

### 2.4 Tomita with degeneracy ordering

Tomita’s version of the algorithm, with the outermost level of recursion ordered in a degeneracy ordering. A combination of Bron–Kerbosch with degeneracy ordering and Tomita.

### 2.5 Tomita on vertex cover

Tomita’s version of the algorithm, with the first iteration only performed on a subset of the $P$ set. The subset is a vertex cover of the graph, which means that for each edge in the graph, at least one of the vertices is in the cover. It is demonstrated in the appendices that this algorithm returns the same set (not necessarily in the same order) of cliques returned by the classic Bron-Kerbosch algorithm.
Chapter 3

Performance

The algorithms were tested on a set of randomly generated graphs, generated with two parameters: $n$ (number of vertexes) and $p$ (chance of connection between nodes). Graphs of different dimension and denseness were generated to compare the performances in different situations. Due to the not optimized nature of the implementations the algorithms were able to solve graphs with parameters up to $n = 1000$ and $p = 30\%$. The search on graphs with higher parameters didn’t terminate on neither of the implementations, and was manually interrupted after 20 to 30 minutes. At the end of the chapter a table shows the results got from each algorithm on each graph of the testing set.

3.1 Classic Bron-Kerbosch

The basic algorithm, as expected, didn’t perform as well as the extensions (except for Bron – Kerbosch with degeneracy ordering) in terms of both execution time and nodes expanded.

3.2 Bron-Kerbosch with degeneracy ordering

This version of the algorithm didn’t gain any advantage over the basic one. It expanded exactly the same number of nodes as ClassicBron – Kerbosch, and run in a slightly bigger time (due to the additional computation of the degeneracy ordering).

3.3 Tomita

Tomita gave overall the best performance. It outperformed all the other algorithms on all of the graphs in terms of computational time, and was the second-best for number of expanded nodes. Compared to ClassicBron – Kerbosch, the nodes expanded were reduced by a factor varying from approx. 2 to approx. 2000. The time was always smaller, sometimes very similar and sometimes by an approx. 2 factor. The only algorithm that expanded less nodes than Tomita was Tomita with degeneracy ordering.
3.4 Tomita with degeneracy ordering

Though the use of a degeneracy ordering didn’t change anything when applied to ClassicBron – Kerbosch, it did make a difference when combined with Tomita. This algorithm expanded the smallest amount of nodes overall, though the number was always very close to the one made by Tomita (the reduction went up to a factor of just 1.05). Though it expanded less nodes, the execution time was always slightly bigger compared to Tomita.

3.5 Tomita on vertex cover

As demonstrated in the appendices, this version of the algorithm were able to produce a complete result by starting the first iteration on a sub-set of the vertexes of the graph (instead of the full graph). The purpose was to expand a smaller amount of nodes. Surprisingly, though, the total amount was always slightly higher compared to the simple Tomita (as well as the running time as well). If on one hand, the vertex cover was almost as big as the graph (95% to 99% of the vertexes), when another algorithm was implemented to calculate a smaller cover (85% to 98% of the vertexes), the number of nodes expanded increased even more. Hence this solution, while accurate, didn’t prove to gain any advantage on neither sparse or dense graphs in the testing set. A performance test on a minimal vertex cover was not made, but it would prove to be useless in terms of speedup, since computing a minimal vertex cover is NP-complete and would add a heavy load on the computational time.
| Alg  | 10-70-00 | clqies: 10 | Max size: 5 | Nodes: 108 | Cpu Time: 1 | 30-90-00 | clqies: 266 | Max size: 18 | Nodes: 1640624 | Cpu Time: 972 | 50-70-00 | clqies: 4879 | Max size: 11 | Nodes: 215701 | Cpu Time: 78 | 100-20-00 | clqies: 879 | Max size: 5 | Nodes: 2484 | Cpu Time: 1 | 100-60-00 | clqies: 57064 | Max size: 12 | Nodes: 1419083 | Cpu Time: 563 | 1000-20-00 | clqies: 1218685 | Max size: 8 | Nodes: 5105221 | Cpu Time: 2128 | 1000-30-00 | clqies: 15299046 | Max size: 9 | Nodes: 103448254 | Cpu Time: 47221 |
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