

Global Escape in Multiparty Sessions

Sara Capecchi

joint work with **Elena Giachino & Nobuko Yoshida**

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Interactional exceptions (Structured Interactional Exceptions for Session Types. Carbone, Honda, Yoshida. CONCUR'08)

not only local but also coordinated actions among communicating peers: exception affects a collection of parallel processes and an escape needs to move into another dialogue in a concerted manner

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 - asynchronous notification to multiple partners
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Coordinated Actions Model

From *Coordinated Exception handling- Romanovsky et al.*

Fault tolerance needs error isolation to define exactly which part of the system to recover, and to prevent errors from unlimited propagation. One way to control complexity is to *restrict interaction and communication*: exception contexts are defined as regions in which the same exceptions are treated in the same way

Coordinated Actions Model

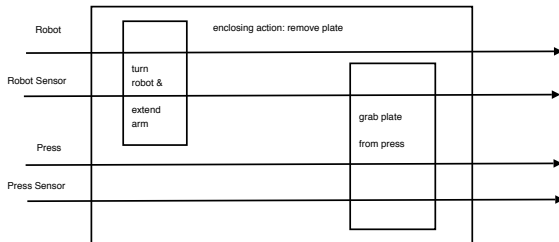
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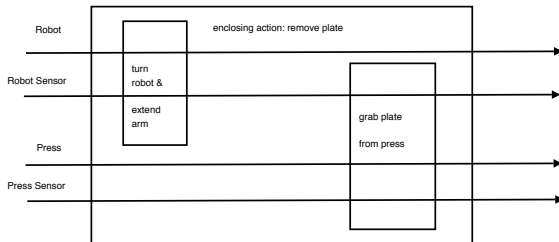
Atomic actions

The activity of a group of components constitutes an atomic action if there are no interactions between that group and the rest of the systems for the duration of the activity

Coordinated Actions

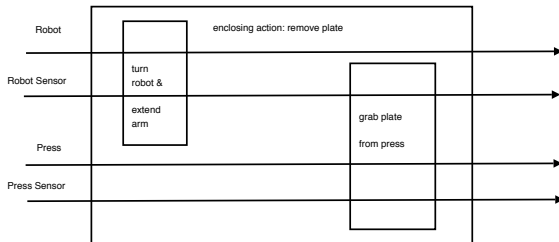


Coordinated Actions



$[(s_1, s_2), [s_1, \gamma_{TR}, \gamma_{HTR}]; [s_1, \gamma_{GP}, \gamma_{HGP}], \gamma_{HRP}]$

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Robot = try(s_1, s_2){try(s_1){ P^R } catch { Q^R }} catch { Q'^R }

RobotSensor = try(s_1, s_2){try(s_1){ P^{RS} } catch { Q^{RS} }; try(s_1){ P'_{RS} } catch { Q'^{RS} }} catch { Q''^{RS} }

Press = try(s_1, s_2){try(s_1){ P^P } catch { Q^P }} catch { Q'^P }

PressSensor = try(s_1, s_2){try(s_1){ P^S } catch { Q^{PS} }} catch { Q'^{PS} }

Syntax and Semantics

P, Q	$::=$	$\bar{a}[2..n](\tilde{s}).P$	Multicast Request		$\text{if } e \text{ then } P \text{ else } P$	Conditional
		$a[p](\tilde{s}).P$	Accept		$P \mid P$	Parallel
		$r!(\tilde{\theta})$	Output		$P; P$	Sequencing
		$r?(\tilde{x}).P$	Input		$\mathbf{0}$	Inaction
		$r \triangleleft l.P$	Select		$(\nu n)P$	Hiding
		$r \triangleright \{l_j : P_j\}_{j \in I}$	Branch		$\text{def } D \text{ in } P$	Recursion
		$\text{try}(\tilde{r})(P) \text{ catch } \{P\}$	Try-Catch		$X(\tilde{\theta}\tilde{s})$	Process call
		$\text{throw}(\tilde{r})$	Throw		$s : L$	Named queue

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[Thr]

$$\Sigma \vdash \text{try}(\tilde{r})\{C[\text{throw}(\tilde{r})] \mid P\} \text{ catch } \{Q\}$$

$$\longrightarrow \Sigma \uplus \text{throw}(\tilde{r}) \vdash \text{try}(\tilde{r})\{C \mid P\} \text{ catch } \{Q\}$$

[RThr]

$$\Sigma, \text{throw}(\tilde{r}) \vdash \text{try}(\tilde{r})\{P\} \text{ catch } \{Q\} \longrightarrow \Sigma, \text{throw}(\tilde{r}) \vdash Q\{s^{\varphi+1}/s^{\varphi}\}_{s^{\varphi} \in \tilde{r}}$$

($\text{throw}(\tilde{r}') \in \Sigma$ implies $\text{try}(\tilde{r}') \dots \notin P$, $\tilde{r}' \subseteq \tilde{r}$)

[ZThr]

$$\Sigma \vdash (\nu \tilde{s})(\prod_i \mathcal{E}_i[\text{try}(\tilde{r})\{\mathbf{0}\} \text{ catch } \{Q_i\}])_{i \in 1..n} \longrightarrow \Sigma \vdash (\nu \tilde{s})(\prod_i \mathcal{E}_i)_{i \in 1..n}$$

($\text{throw}(\tilde{r}) \notin \Sigma$)

Typing

Partial	γ	$::=$	$p_1 \rightarrow p_2 : k\langle\tilde{S}\rangle \mid p_1 \rightarrow p_2 : k\{l_i : \gamma_i\}_{i \in I} \mid$ $[\tilde{k}, \gamma, \gamma] \mid \gamma; \gamma \mid \gamma \parallel \gamma \mid \mu\mathbf{t}.\gamma \mid \mathbf{t}$
Global	G	$::=$	$\gamma; \text{end} \mid \text{end}$
Sorts	S	$::=$	$\text{bool} \mid \dots \mid \langle G \rangle$

Goals:

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Goals:

- to check that the enclosed try-catch block is listening on a smaller set of channels: independence of the components w.r.t. exceptions

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Goals:

- to check that the enclosed try-catch block is listening on a smaller set of channels: independence of the components w.r.t. exceptions
- to check that no session request or accept occurs inside a try-catch block

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- **safe**: linearity of communications inside sessions and absence of communication mismatch are enforced carrying out fundamental properties of session types

We ensure these properties using:

- an asynchronous linguistic construct for exceptions signalling
- multi-level queues